

Gossip in a Smartphone Peer-to-Peer Network

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Abstract

In this paper, we study the fundamental problem of gossip in the *mobile telephone model*: a recently introduced variation of the classical *telephone model* modified to better describe the local peer-to-peer communication services implemented in many popular smartphone operating systems. In more detail, the mobile telephone model differs from the classical telephone model in three ways: (1) each device can participate in at most one connection per round; (2) the network topology can undergo a parameterized rate of change; and (3) devices can advertise a parameterized number of bits about their state to their neighbors in each round before connection attempts are initiated. We begin by describing and analyzing new randomized gossip algorithms in this model under the harsh assumption of a network topology that can change completely in every round. We prove a significant time complexity gap between the case where nodes can advertise 0 bits to their neighbors in each round, and the case where nodes can advertise 1 bit. For the latter assumption, we present two solutions: the first depends on a shared randomness source, while the second eliminates this assumption using a pseudorandomness generator we prove to exist with a novel generalization of a classical result from the study of two-party communication complexity. We then turn our attention to the easier case where the topology graph is stable, and describe and analyze a new gossip algorithm that provides a substantial performance improvement for many parameters. We conclude by studying a relaxed version of gossip in which it is only necessary for nodes to each learn a specified fraction of the messages in the system. We prove that our existing algorithms for dynamic network topologies and a single advertising bit solve this relaxed version up to a polynomial factor faster (in network size) for many parameters. These are the first known gossip results for the mobile telephone model, and they significantly expand our understanding of how to communicate and coordinate in this increasingly relevant setting.

1 Introduction

This paper describes and analyzes new gossip algorithms in the mobile telephone model: an abstraction that captures the local device-to-device communication capabilities available in most smartphone operating systems; e.g., as implemented by services such as Bluetooth LE [17], WiFi Direct [4], and Apple’s Multipeer Connectivity framework [20].

Motivation. Smartphones are a ubiquitous communication platform: there are currently over 3.9 billion smartphone subscriptions worldwide [2]. Most smartphone communication leverages one-hop radio links to cell towers or WiFi access points. In recent years, however, the major smartphone operating systems have included increasingly stable and useful support for local peer-to-peer communication that allows a device to talk directly to a nearby device (using local radio broadcast) while avoiding cellular and WiFi infrastructure.

The ability to create these local links, combined with the ubiquity of smartphones, enables scenarios in which large groups of nearby smartphone users run applications that create peer-to-peer meshes supporting infrastructure-free networking. There are many possible motivations for these smartphone peer-to-peer networks. For example, they can support communication in settings where network infrastructure is *censored*

(e.g., government protests), *overwhelmed* (e.g., a large festival or march), or *unavailable* (e.g., after a disaster or at a remote event). In addition, in developing countries, cellular data minutes are often bought in blocks and carefully conserved—increasing interest in networking operations that do not require cellular infrastructure.

To further validate the potential usefulness of smartphone peer-to-peer networks, consider the FireChat application, which implements group chat using smartphone peer-to-peer services. In the few years since its initial release, it has been widely adopted in over 120 countries and has been used successfully in multiple government protests, festivals (e.g., at Burning Man, which is held far from cell towers), and disaster scenarios [1].

Developing useful applications for this smartphone peer-to-peer setting requires distributed algorithms that can provide global reliability and efficiency guarantees on top of an unpredictable collection of local links. As detailed below, the models that describe this emerging setting are sufficiently different from existing models that new algorithms and analysis techniques are required. This paper addresses this need by describing and analyzing new gossip algorithms for this important setting.

The Mobile Telephone Model. The mobile telephone model studied in this paper was introduced in recent work [11, 22]. It is a variant of the classical telephone peer-to-peer model (e.g., [9, 10, 12, 15, 13, 5, 16, 8, 14]) modified to better describe the capabilities and constraints of existing smartphone peer-to-peer services. The details of the mobile telephone model are inspired, in particular, by the current specifications of Apple’s Multipeer Connectivity framework [20]: a peer-to-peer service available in every iOS version since iOS 7 that allows nodes to advertise services, discover nearby advertisers, and attempt to connect to nearby advertisers, using only local radio broadcast. (The definition of the classical telephone model, and differences between the classical telephone and mobile telephone model, are detailed and discussed below in the related work section.)

In more detail, the mobile telephone model abstracts the basic *scan-and-connect* dynamics of the Multipeer framework as follows. Time proceeds in synchronous rounds. In each round, a connected graph describes the underlying network topology for that round. At the beginning of each round, each device (also called a *node* in the following) learns its neighbors in the topology graph (e.g., as the result of a scan). Each device can then attempt to initiate a connection with a neighbor. Each node can support at most one connection—so if multiple nodes attempt to connect with the same target, only one connection will succeed. If two nodes connect, they can perform a bounded amount of reliable communication before the round ends.

We parameterize this model with a *tag length* $b \geq 0$. At the beginning of each round, each node can choose a *tag* consisting of b bits to advertise. When performing a scan, each node learns both the ids and chosen tags of its neighbors (where $b = 0$ means there are no tags). These tags can change from round to round. In our previous study of rumor spreading with parameter $b = 1$ [11], for example, at the beginning of a given round, each node that already knows the rumor advertises a 1 with its tag, while other nodes advertise a 0. This simplified the rumor spreading task by enabling nodes that know the rumor to only attempt to connect to nodes that do not. This capability of nodes to use tags to deliver limited information to their neighbors is motivated by the ability of devices to choose and change their service advertisements in the Multipeer framework.

We also parameterize the model with a *stability factor* $\tau \geq 1$. The underlying network topology must stay stable for at least τ rounds between changes. For $\tau = 1$, for example, the network topology can change completely in every round, while for $\tau = \infty$, the topology never changes. There exist finer-grained approaches for capturing intermediate levels of stability (e.g., T -interval connectivity [19]), but in this paper we study only the two extreme cases of fully dynamic and fully stable topologies, so our simpler stability factor definition is sufficient. The need to model topology changes is motivated by the inherently mobile nature of the smartphone setting.

Results. In this paper, we describe and analyze new algorithms for the *gossip* problem in the mobile telephone model with respect to different model parameter and algorithm assumptions. This problem assumes a subset of nodes start with messages (also called *tokens*). The goal is to spread these messages to the entire network.

| Assumptions | Algorithm | Gossip Round Complexity |
|---|----------------|---|
| Standard Gossip | | |
| $b = 0, \tau \geq 1$ | BlindMatch | $O((1/\alpha)k\Delta^2 \log^2 n)$ |
| $b = 1, \tau \geq 1$ | SharedBit* | $O(kn)$ |
| $b = 1, \tau \geq 1$ | SimSharedBit** | $O(kn + (1/\alpha)\Delta^{1/\tau} \log^6 n)$ |
| $b = 1, \tau = \infty$ | CrowdedBin | $O((k/\alpha) \log^6 n)$ |
| ϵ -Gossip ($0 < \epsilon < 1$) | | |
| $b = 1, \tau \geq 1$ | SharedBit* | $O\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha}\right)$ |

Figure 1: **A summary of gossip and ϵ -gossip round complexity bounds proved in this paper.** (In the ϵ -gossip problem, it is assumed that every node starts with a message, but each node need only learn an ϵ -fraction of the n total messages.) In the following: n is the network size, k is the number of gossip messages, α and Δ are the vertex expansion and maximum degree, respectively, of the network topology graph, b is the tag length, and τ is the stability factor. All results hold with high probability in n (i.e., at least $1 - 1/n$). Notice, the result for $b = 0$ and $\tau \geq 1$ is the best known result even for the easier case of $b = 0$ and $\tau = \infty$. (*) The SharedBit algorithm (alone among all algorithms studied) requires shared randomness. (**) The SimSharedBit algorithm is existential in the sense that it depends on a pseudorandomness generator that we prove exists in Section 5.

Gossip is fundamental in distributed computing and is considered particularly important for ad hoc networks such as the smartphone meshes studied in this paper (c.f., the introductory discussion in [23]).

Below (and in Figure 1) we state and discuss our main results. In the following, let $n > 1$ be the network size and $k, 1 \leq k \leq n$, be the number of tokens in the system. For a given topology graph, we use α to describe its vertex expansion (see the model discussion below) and Δ to describe its maximum degree.¹ We assume the topologies are connected. All round complexity results hold with high probability in n (i.e., probability at least $1 - 1/n$).

We start by considering the difficult setting where $b = 0$ and $\tau = 1$; i.e., nodes cannot use tags and the network topology graph can change completely in each round. In Section 4, we describe and analyze a natural strategy for this setting called BlindMatch, which has nodes select neighbors with uniform randomness to send connection attempts.² We prove that BlindMatch solves gossip in $O((1/\alpha)k\Delta^2 \log^2 n)$ rounds. This bound might seem pessimistic at first glance, but it is known that disseminating even a single message in the mobile telephone model with this strategy can take $\Omega(\Delta^2/\sqrt{\alpha})$ rounds in some networks [22]. Indeed, this lower bound holds even for the easier assumption that $\tau = \infty$. Accordingly, we do not consider $b = 0$ and $\tau = \infty$ as a distinct case in this paper. (To provide intuition for why $\Omega(\Delta^2)$ rounds are sometimes necessary, consider two stars centered on u and v , respectively, where each star has around Δ points and u and v are connected by an edge. Assume u starts with a gossip message. For v to receive this message two events must happen: (1) u selects v for a connection; and (2) v accepts u 's connection from all incoming connections in that round. The first event occurs with probability $\approx 1/\Delta$, and because v can expect a constant fraction of its neighbors to send it connection attempts in any given round, the second event also occurs with probability $\approx 1/\Delta$.) Our BlindMatch result provides the benchmark against which we attempt to improve with the algorithms that follow.

In Section 5, we consider the case where $b = 1$ and $\tau \geq 1$; i.e., the network can still change completely in each round, but now nodes can advertise a single bit to their neighbors. We begin by describing and

¹If the topology is dynamic, then α is defined as the minimum expansion over all rounds, and Δ is defined as the largest maximum degree over all rounds.

²This is essentially the well-known PUSH-PULL strategy from the classical telephone model with the key exception that in our model if a node receives multiple connection attempts, only one succeeds. As discussed in the related work and Section 4, this well-motivated model change requires new analysis techniques to understand information propagation.

analyzing an algorithm called SharedBit. This algorithm assumes a shared randomness source which is used to implement (essentially) a random hash function that allows nodes to hash their current set of known messages to a single bit to be used as their one-bit advertising tag. The key guarantee of this function is that nodes with the same sets advertise the same bit, and nodes with different sets have a constant probability of advertising different bits. This helps nodes seek out productive connections with neighbors (e.g., connections in which at least one node learns something new). We prove that SharedBit solves gossip in $O(kn)$ rounds.

We next seek to eliminate the shared randomness assumption. To do so, we describe SimSharedBit which solves gossip in $O(kn + (1/\alpha)\Delta^{1/\tau} \log^6 n)$ rounds, without assuming a shared randomness source. Notice, because $\alpha \geq 2/n$ and $\Delta \leq n$, this solution is always within log factors of the SharedBit for large k , and for small k it is still comparable for many values of α , Δ , and/or τ .

The SimSharedBit algorithm depends on a novel generalization of *Newman’s Theorem* [21]—a well-known result on public randomness simulation from the study of two-party communication complexity. We prove that there exists an appropriate pseudorandom number generator that can provide sufficient randomness for the SharedBit strategy. We then elect a leader in $O((1/\alpha)\Delta^{1/\tau} \log^6 n)$ rounds using an algorithm from [22], and use this leader to disseminate a small generator seed. We note that our generalization of Newman’s Theorem is potentially of standalone interest as the techniques we introduced can be used to study pseudorandomness in many different graph algorithm settings.

In Section 6, we consider the impact of topology changes on gossip time. In particular, we consider the case where $b = 1$ and $\tau = \infty$; i.e., the network topology is stable. We describe and analyze CrowdedBin, an algorithm that solves gossip in $O((1/\alpha)k \log^6 n)$ rounds. This algorithm matches or outperforms the $O(kn)$ round complexity of SharedBit for all α values (ignoring log factors). For well-connected networks (e.g., constant α), it performs almost a factor of n faster. These results hint that large increases to stability are more valuable to gossip algorithms than large increases to tag length (for most of our solutions, increasing b beyond 1 only improves performance by at most logarithmic factors).

The benefit of stable network topologies is that nodes can transmit larger amounts of information about their current state to their neighbors by using their single bit advertisement tag over multiple rounds. CrowdedBin leverages this capability to help nodes efficiently converge on an accurate estimate of k —which is not known in advance. This process depends on nodes testing guesses by throwing their tokens into a number of bins corresponding to the current guess, and then seeking/spreading evidence of crowding (as established by a new balls-in-bins algorithm described in Section 6). Once all nodes learn an appropriate guess of k , CrowdedBin deploys an efficient parallel rumor spreading strategy to efficiently disseminate the k tokens.

Finally, we consider the ϵ -gossip problem, which is parameterized with a fraction ϵ , $0 < \epsilon < 1$, assumes that $k = n$, and relaxes the gossip problem to require only that every node receives at least $n\epsilon$ of the n total tokens. This variation is useful for settings where it is sufficient for nodes to learn *enough* rumors to complete the task at hand; e.g., when an algorithm requires responses from only a majority quorum of nodes.

In Section 7, we re-analyze the SharedBit gossip algorithm from Section 5. Deploying a novel argument based on finding productive “coalitions” of nodes, we show that SharedBit solves ϵ -gossip in $O\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha}\right)$ rounds. Recall that SharedBit solves regular gossip in $O(n^2)$ rounds under the $k = n$ assumption. Therefore, when ϵ is a constant fraction and the network is well-connected (α is large), SharedBit solves ϵ -gossip up to a (sub-linear) polynomial factor faster than the standard gossip problem.

Related Work. The mobile telephone model used in this paper was first introduced in a study of rumor spreading by Ghaffari and Newport [11]. We also recently studied leader election in this same model [22]. As noted, the mobile telephone model is a variation of the classical telephone model (first introduced by Frieze and Grimmett [9]) adapted to better describe smartphone peer-to-peer networks. The mobile model differs from the classical model in two ways: (1) the classical model implicitly fixes $b = 0$ and (typically) $\tau = \infty$; and (2) the classical model allows nodes to accept an unbounded number of incoming connections.

It is important to emphasize that most of the well-known bounds in the classical model depend on this

assumption of unbounded connections, and removing this assumption requires new analysis techniques; c.f., the discussion in [11]. We note that work by Daum et al. [6] (which preceded [11, 22]) also pointed out the dependence of existing telephone model bounds on unbounded concurrent connections.

A fundamental problem in peer-to-peer networks is *rumor spreading*, in which a single message must be disseminated from a designated source to all nodes (this is equivalent to gossip with $k = 1$). This problem is well-understood in the classical telephone model, where spreading times are often expressed with respect to spectral properties of the network topology graph such as graph conductance (e.g., [13]) and vertex expansion (e.g., [5, 16, 8, 14]). This existing work established that efficient rumor spreading is possible with respect to both graph properties in the classical model. In [11], we studied this problem in the mobile telephone model. We proved that efficient rumor spreading with respect to conductance *is not* possible in the mobile telephone model, but efficient spreading with respect to vertex expansion *is* possible. We then proved that for $b = 1$ and $\tau \geq 1$, a simple random spreading strategy solves the problem in $O((1/\alpha)\Delta^{1/\tau}\text{polylog}(n))$ rounds—matching the tight $\Theta((1/\alpha)\log^2 n)$ result from the classical telephone model within log factors for $\tau \geq \log \Delta$. In [22], we built on these results to solve leader election in similar asymptotic time.

Though gossip is well-studied in peer-to-peer models (see [23] for a good overview), little is known about how to tackle the problem in the mobile telephone model, where concurrent connections are now bounded but nodes can leverage advertising tags.³ Finally, we note that there are application similarities between gossip in the mobile telephone model and existing reliable multicast solutions for mobile ad hoc (e.g., [18]) and delay-tolerant (e.g., [3]) networks. These existing solutions, however, tend to be empirically evaluated and depend on the ability to predict information about link behavior (e.g., predicted link duration or an advance schedule of when given links will be present).

2 Model and Problem

We describe a smartphone peer-to-peer network using the *mobile telephone model*. As elaborated in the introduction, the basic properties of this model—including its scan-and-connect behavior, dynamic topologies, and the nodes’ ability to advertise a bounded tag—are inspired in particular by the behavior of the Apple Multipeer Connectivity framework for smartphone peer-to-peer networking.

In more detail, we assume executions proceed in synchronous rounds labeled $1, 2, \dots$. We assume all nodes start in the same round. We describe a peer-to-peer network topology in each round r as an undirected connected graph $G_r = (V, E_r)$ that can change from round to round, constrained by the stability factor (see below). We call the sequence of graphs G_1, G_2, \dots that describe the evolving topology a dynamic graph. We assume the definition of the dynamic graph is fixed at the beginning of the execution.

We assume a computational process (also called a *node* in the following) is assigned to each vertex in V , and use $n = |V|$ to indicate the network size. At the beginning of each round r , we assume each node u learns its neighbor set $N(u)$ in G_r . Node u can then select at most one node from $N(u)$ and send a connection proposal. A node that sends a proposal cannot also receive a proposal. If a node v does not send a proposal, and at least one neighbor sends a proposal to v , then v can *accept* an incoming proposal. There are different ways to model how v selects a proposal to accept. In this paper, for simplicity, we assume v accepts an incoming proposal selected with uniform randomness from the incoming proposals. If node v accepts a proposal from node u , the two nodes are *connected* and can perform a bounded amount of interactive communication to conclude the round. We leave the specific bound on communication per connection as a problem parameter.

³It might be tempting to simply run k parallel instances of the rumor spreading strategy from [11] to gossip k messages, but this approach fails for three reasons: (1) our model allows only $O(1)$ tokens to be sent per connection per round; (2) each of the k instances requires its own advertising tag bit, whereas all of our new gossip results focus on the case where $b \leq 1$; and (3) nodes do not know k in advance. Accordingly, most results presented in this paper require substantial technical novelty.

Model Parameters. We parameterize the mobile telephone model with two integers, a *tag length* $b \geq 0$ and a *stability factor* $\tau \geq 1$. We allow each node to select a *tag* containing b bits to advertise at the beginning of each round. That is, if node u chooses tag b_u at the beginning of a round, all neighbors of u learn b_u before making their connection decisions in this round. A node can change its tag from round to round.

We also allow for the possibility of the network topology changing between rounds. We bound the allowable changes with a stability factor $\tau \geq 1$. For a given τ , the dynamic graph describing the changing topology must satisfy the property that at least τ rounds must pass between any changes to the topology. For $\tau = 1$, the graph can change arbitrarily in every round. We use the convention of stating $\tau = \infty$ to indicate the graph never changes.

Vertex Expansion and Maximum Degree. Several of our results express time complexity bounds with respect to the *vertex expansion* α of the dynamic graph describing the network topology. To define α , we first review a standard definition of vertex expansion for a fixed static unconnected graph $G = (V, E)$.

For a given $S \subseteq V$, define the *boundary* of S , indicated ∂S , as follows: $\partial S = \{v \in V \setminus S : N(v) \cap S \neq \emptyset\}$: that is, ∂S is the set of nodes not in S that are directly connected to S by an edge in E . Next define $\alpha(S) = |\partial S|/|S|$. As in [14, 11], we define the *vertex expansion* $\alpha(G)$ of our static graph $G = (V, E)$ as follows:

$$\alpha(G) = \min_{S \subseteq V, 0 < |S| \leq n/2} \alpha(S).$$

Notice that despite the possibility of $\alpha(S) > 1$ for some S , we always have $\alpha(G) \leq 1$. We define the vertex expansion α of a *dynamic* graph G_1, G_2, \dots , to be the minimum vertex expansion over all of the dynamic graph's constituent static graphs (i.e., $\alpha = \min\{\alpha(G_i) : i \geq 1\}$).

Similarly, we define the maximum degree Δ of a dynamic graph to be the maximum degree over all of the dynamic graph's constituent static graphs.

The Gossip Problem. The gossip problem assumes each node is provided an upper bound⁴ $N \geq n$ on the network size and a unique ID (UID) from $[N]$. The problem assumes some subset of nodes begins with a gossip message to spread (which we also call a *token*). We use k to describe the size of this subset and assume that k is not known to the nodes in advance. A given node can start the execution with multiple tokens, but no token starts at more than one node. We treat gossip tokens as comparable black boxes that can only be communicated between nodes through connections (e.g., a node cannot transmit a gossip token to a neighbor by spelling it out bit by bit using its advertising tags). If a node begins an execution with a token or has received the token through a connection, we say that the node *owns*, *knows* or has *learned* that token. We assume that a pair of connected nodes can exchange at most $O(1)$ tokens and $O(\text{polylog}(N))$ additional bits during a one round connection.

Solving the Gossip Problem. The gossip problem requires all nodes to learn all k tokens. Formally, we say a distributed algorithm *solves the gossip problem* in $f(n, k, \alpha, b, \tau)$ rounds, if with probability at least $1 - 1/n$, all nodes know all k tokens by round $f(n, k, \alpha, b, \tau)$ when executed in a network of size n , with k tokens, vertex expansion α , tag length b , and stability factor τ . We omit parameters when not relevant to the bound.

Probability Preliminaries. The analyses that follow leverage the following well-known probability results:

Theorem 2.1. For $p \in [0, 1]$, we have $(1 - p) \leq e^{-p}$ and $(1 + p) \geq 2^p$.

Theorem 2.2 (Chernoff Bound: Lower Bound Form). Let $Y = \sum_{i=1}^t X_i$ be the sum of $t > 0$ i.i.d. random

⁴For the sake of concision, the results described in the introduction and Figure 1 make the standard assumption that N is a polynomial upper bound on n , allowing us to replace N with n within logarithmic factors inside asymptotic notation. In the formal theorem statements for these results, however, we avoid this simplification and leave N in place where used—enabling a slightly finer-grained understanding of the impact of the looseness of network size estimation on our complexity guarantees.

indicator variables X_1, X_2, \dots, X_t , and let $\mu = E(Y)$. Fix some fraction δ , $0 < \delta < 1$. It follows:

$$\Pr(X \leq (1 - \delta)\mu) \leq e^{-\frac{\delta^2 \mu}{2}}.$$

Theorem 2.3 (Chernoff Bound: Upper Bound Form). *Let $Y = \sum_{i=1}^t X_i$ be the sum of $t > 0$ i.i.d. random indicator variables X_1, X_2, \dots, X_t , and let $\mu = E(Y)$. Fix some value $\delta > 1$. It follows:*

$$\Pr(X \geq (1 + \delta)\mu) \leq e^{-\frac{\delta \mu}{3}}.$$

Theorem 2.4 (Chernoff-Hoeffding Bound). *Let X_1, X_2, \dots, X_t , be $t \geq 1$ i.i.d. random indicator variables. Let $\mu = E(X_i)$ and fix some $\delta > 0$. It follows:*

$$\Pr\left(\frac{1}{t} \sum_{i=1}^t X_i \geq \mu + \delta\right) \leq e^{-2\delta^2 t}.$$

Theorem 2.5 (Markov's Inequality). *Let X be a nonnegative random variable and $a > 0$ be a real number. It follows:*

$$\Pr(X \geq a) \leq \frac{E(X)}{a}.$$

3 Token Transfer Subroutine

An obstacle to solving gossip in the mobile telephone model is deciding which tokens to exchange between two connected nodes. In more detail, once two nodes u and v with respective token sets T_u and T_v connect, even if they *know* $T_u \neq T_v$, they must still identify at least one token $t \notin T_u \cap T_v$ to transfer for this round of gossip to be useful. Complicating this task is the model restriction that u and v can only exchange $O(\text{polylog}(N))$ bits before deciding which tokens (if any) to transfer. This is not (nearly) enough bits to encode a full token set (a simple counting argument establishes that every coding scheme will require $\Omega(N)$ bits for some sets). Therefore, a more efficient routine is needed to implement this useful token transfer.

Here we describe a *transfer subroutine* that solves this problem and is used by multiple gossip algorithms described in this paper. This routine, which we call $Transfer(\epsilon)$, for an error bound ϵ , $0 < \epsilon < 1$, is a straightforward application of an existing algorithmic tool from the literature on two-party communication complexity. It guarantees the following: if $Transfer(\epsilon)$ is called by two connected nodes u and v , with respective token sets T_u and T_v , and $T_u \neq T_v$, then with probability at least $1 - \epsilon$ the smallest token t (by a predetermined token ordering) that is *not* in $T_u \cap T_v$, will be transferred by the node that knows t to the node that does not. This routine requires u and v to exchange only $O(\log^2 N \cdot \log(\frac{\log N}{\epsilon}))$ controls bits in addition to token t . It also assumes some fixed ordering on tokens.

Equality Testing. We use one of the many known existing solutions to the *set equality* (EQ) problem from the study of two-party communication complexity. In our setting with u and v (described) above, these existing solutions provide u and v a way to test the equality of T_u and T_v , and they offer the following guarantee: if $T_u = T_v$, then u and v will correctly determine their sets are equal with probability 1, else if $T_u \neq T_v$ then u and v will *erroneously* determine their sets are equal with probability no more than $1/2$. These existing solutions assume only private randomness and require u and v to exchange no more than $O(\log N)$ bits. A nice property of most such solutions is that each trial is independent. Therefore, if u and v repeat this test c times, for some integer $c \geq 1$, then the error probability drops exponentially fast with c to 2^{-c} . Let us fix one such equality testing routine and call it $EQTest(c)$, where parameter $c \geq 1$ determines how many trials to execute in testing the equality.

The Transfer Subroutine. We now deploy $EQTest(\epsilon')$, for $\epsilon' = \lceil \log(\frac{\log N}{\epsilon}) \rceil$, as a subroutine to implement the $Transfer(\epsilon)$ routine. In particular, recall that for a given u and v , we can understand T_u and T_v to both be subsets of the values in $[N]$ (as each node in the network can label each token with its UID from $[N]$ at the beginning of the execution). Our goal is to identify the smallest location value in $[N]$ that is in $T_u \cup T_v$ but not in $T_u \cap T_v$. To do so, we can implement a binary search over the interval $[N]$, using $EQTest(\epsilon')$ to test the equality of the interval in question between u and v . In more detail:

Transfer(ϵ):

$a \leftarrow 1; b \leftarrow N$

while $a \neq b$

$result \leftarrow \mathbf{EQTest}(\epsilon')$ executed on $T_u \cap [a, \lfloor b/2 \rfloor]$ and $T_v \cap [a, \lfloor b/2 \rfloor]$

if $result = \mathit{notequal}$ **then** $b \leftarrow \lfloor b/2 \rfloor$ **else** $a \leftarrow \lfloor b/2 \rfloor + 1$

transfer token a to the other node if you know token a

The above logic implements a basic binary search over the interval $[N]$ to identify the smallest value in this interval that is in exactly one of the two sets T_u and T_v . If every call to $EQTest$ succeeds then the search succeeds and $Transfer$ behaves correctly. There are at most $\log N$ calls to $EQTest$, each of which fails with probability $2^{-\epsilon'} \leq \epsilon / \log N$. Therefore, by a union bound, the probability that at least one of the $\log N$ calls to $EQTest$ fails is less than ϵ , as claimed. From a communication complexity perspective, each call to $EQTest(\epsilon')$ requires $O(\log N \cdot \epsilon') = O(\log N \cdot \log(\log N / \epsilon))$ bits, and we make $\log N$ such calls. Therefore, the total communication complexity is in $O(\log^2 N \cdot \log(\frac{\log N}{\epsilon}))$, as claimed.

4 Gossip with $b = 0$ and $\tau \geq 1$

Here we consider the most difficult case for gossip in our model: nodes cannot advertise any information to their neighbors ($b = 0$), and the network topology graph can change arbitrarily in every round ($\tau = 1$). We will study the straightforward strategy in which nodes randomly select neighbors for attempted connections and then use the token transfer routine to select tokens to exchange during successful connections. We will show this strategy solves gossip in $O((1/\alpha)k\Delta^2 \log^2 N)$ rounds when executed with k tokens in a network graph with expansion α and maximum degree Δ . This result might seem pessimistically large at first glance, but as shown in [22], there are networks in which simple blind connection strategies like those implemented here do require $\Omega(\Delta^2 / \sqrt{\alpha})$ rounds to spread even a single message.

The BlindMatch Gossip Algorithm. At the beginning of each round $r \geq 1$, each node $u \in V$ flips a fair coin to decide whether to be a *sender* or a *receiver* in r . If u decides to be a sender, it selects a neighbor uniformly from among its neighbors in this round and sends it a connection proposal. If u decides to be a receiver it waits to receive proposals. If two nodes u and v connect, they execute the token transfer subroutine which attempts to transfer the smallest token in $(T_u(r) \cup T_v(r)) \setminus (T_u(r) \cap T_v(r))$, assuming such a token exists.

Analysis. We now prove the below theorem concerning about the performance of the BlindMatch algorithm. The proof adapts our recent analysis of leader election strategies in the mobile telephone model under the assumption that $b = 0$ [22]. The main contribution of this section, therefore, is less technical than it is the establishment of a baseline against which to compare the other results studied in this paper.

Theorem 4.1. *The BlindMatch gossip algorithm solves the gossip problem in $O((1/\alpha)k\Delta^2 \log^2 N)$ rounds when executed with tag length $b = 0$ in a network with stability $\tau \geq 1$.*

Proof. In [22], we study a leader election algorithm called BlindGossip that essentially matches the behavior

of BlindMatch. As in BlindMatch, this algorithm has each node in each round flip a coin to decide whether or not to send or receive, and senders choose a neighbor uniformly to send a connection proposal. If two nodes connect, they transfer the smallest UIDs they have seen so far in the execution. In [22], we prove that this strategy will disseminate the smallest UID in the network to all nodes in the network in $O((1/\alpha)\Delta^2 \log^2 N)$ rounds, with high probability in N . This existing analysis follows the progress of the smallest token in the network showing that after this many rounds it will have spread to all nodes.

In BlindMatch, by contrast, a connected pair executes the transfer routine to attempt to transfer the smallest token known by one but not both of the connected nodes. It follows, therefore, that under the assumption that the transfer routine works correctly every time it is called, BlindMatch will spread the smallest token in the network to all nodes in the time stated above. Once this has been accomplished, however, we can turn our attention to the second smallest token (once all nodes know the smallest token, the transfer routine will always transfer the second smallest when a node that knows the second smallest is connected to a node that does not). After the above number of rounds, the second smallest token will also have spread. We repeat this process for all k tokens to get the final $O((1/\alpha)k\Delta^2 \log^2 N)$ time claimed above. \square

5 Gossip with $b = 1$ and $\tau \geq 1$

Here we describe and analyze two gossip algorithms that now assume $b = 1$. The first, called SharedBit, assumes shared randomness, while the second, SimSharedBit, does not. Both solutions offer a substantial time complexity improvement over the BlindMatch algorithm for many graph parameters.

Discussion: Shared Randomness. For the sake of clarity, we begin by making a strong assumption that we will subsequently eliminate: the nodes have access to a shared randomness source. In more detail, we assume at the beginning of the execution a bit string \hat{r} of length $T = O(N^3 \log N)$ is selected with uniform randomness from the space \mathcal{R} of all bit strings of this length. All nodes can access \hat{r} . This shared random string simplifies the description and analysis of an efficient gossip algorithm for the assumptions tackled in this section. In particular, the key challenge for gossip in this setting is generating useful 1-bit advertising tags in each round. We would like nodes with the same token set to generate the *same* bit (so they will know not to attempt to connect to each other), while pairs of nearby nodes with different token sets to have a reasonable probability of generating *different* bits (so they will know a connection would prove useful). Shared randomness enables this property as each node can associate the same fresh random bit for each token in a given round, and the bit advertised for a given set can simply consist of the sum of the bits associated with tokens in the set (mod 2).

Discussion: Eliminating the Shared Randomness Assumption. The assumption of shared randomness might be unrealistic in some settings. With this in mind, we will then proceed to show how to eliminate this assumption by simulating public randomness using a much smaller number of private random bits that disseminate quickly throughout the network. The core strategy of this simulation borrows and expands key ideas from the proof of *Newman's Theorem* (e.g., [21])—a well-known result on public randomness simulation from the study of two-party communication complexity. Our result is existential in the sense that it establishes that there exists an efficient simulation of our shared randomness that works well enough. An equivalent formulation of this result in the language of pseudorandomness is that there exists a pseudorandom number generator that can generate the needed number of bits with a seed sufficiently small to fit in our message size bound.

5.1 Shared Randomness

Here we describe and analyze the SharedBit gossip algorithm.

The SharedBit Gossip Algorithm. Let \hat{r} be a shared random string of length $cN^3(\lceil \log N \rceil + 1)$ bits. We

assume nodes partition \hat{r} into cN^2 groups each consisting of N bundles (one for each id that might show up in the network) that each contain $\lceil \log N \rceil + 1$ bits. We label these groups $1, 2, \dots, cN^2$, and label the bundles within a given group $1, 2, \dots, N$.

At the beginning of each round $r \leq cN^2$, node u must decide which bit to advertise to its neighbors (i.e., what value to select for $b_u(r)$). If $T_u(r)$ is empty, then u advertises 0 (i.e., $b_u(r) = 0$). Otherwise, node u calculates its advertisement by first extracting a shared bit from \hat{r} to assign to each $t \in T_u(r)$. In particular, for each such $t \in T_u(r)$, u sets its bit, indicated $t.bit$, to be the first bit in bundle t of group r from \hat{r} . Node u then calculates the bit $b_u(r)$ to advertise in this round as follows:

$$b_u(r) = \left(\sum_{t \in T_u(r)} t.bit \right) \bmod 2.$$

If $b_u(r) = 0$ then u will receive connection proposals in this round. If $b_u(r) = 1$ and u has at least one neighbor advertising 0, then u will choose one these neighbors with uniform randomness and send it a connection proposal. To make this random choice, u uses the random bits in positions 2 to $\lceil \log N + 1 \rceil$ in the bundle corresponding to its id in group r of \hat{r} .⁵

If two nodes u and v connect in round r , they will deploy the token transfer subroutine, with parameter $\epsilon = n^{-c_t}$, for some sufficiently large constant $c_t \geq 1$ we fix in the analysis. This routine will identify and transfer the smallest token in $(T_u(r) \cup T_v(r)) \setminus (T_u(r) \cap T_v(r))$, without sending more than $\text{polylog}(N)$ bits in the interaction (the bound enforced by our model). Recall, this *transfer subroutine* is probabilistic and succeeds in identifying a token to transfer with probability at least $1 - \epsilon$. Once the algorithm proceeds past round cN^2 it can terminate or fall back to a simpler behavior (such as our algorithm for $b = 0$), or recycle back to the beginning of the shared string.

Analysis. Our goal is to prove the following theorem regarding the SharedBit gossip algorithm:

Theorem 5.1. *The SharedBit gossip algorithm solves the gossip problem in $O(kn)$ rounds when executed with shared randomness and tag length $b = 1$, in a network with stability $\tau \geq 1$.*

To setup our analysis, recall that we define $T_u(r)$ for node u and round $r \geq 1$, to be the set of tokens u knows at the beginning of round r , and use $b_u(r)$ to indicate the bit advertised by u in round r . Also recall that cN^2 is the maximum number of rounds for which the shared string \hat{r} contains bits (our below analysis will specify the needed lower bound on constant $c \geq 1$), and that $t.bit$, for a given token t and a fixed round, describes the shared random bit extracted from \hat{r} and assigned to t in this round.

We begin with the following lemma, which bounds the probabilistic behavior of the advertising tags generated using a given shared \hat{r} .

Lemma 5.2. *Fix two nodes $u, v \in V$, $u \neq v$, and a round r , $1 \leq r \leq cN^2$. Fix a $r - 1$ round execution of SharedBit, and let $p = \Pr(b_u(r) \neq b_v(r))$ be the probability (defined over the random selection of the relevant bits in \hat{r}) that u and v generate different advertising bits in round r . If $T_u(r) = T_v(r)$ then $p = 0$, else if $T_u(r) \neq T_v(r)$, then $p = 1/2$.*

Proof. If $T_u(r) = T_v(r)$ then by definition of the algorithm $b_u(r) = b_v(r)$. We turn our attention, therefore, to the remaining case where $T_u(r) \neq T_v(r)$. In the following, for a given non-empty token set T , define:

$$adv_r(T) = \left(\sum_{t \in T} t.bit \right) \bmod 2.$$

⁵The reason we have u use shared random bits to select the receiver of its proposal is because it will simplify our subsequent effort to eliminate shared randomness for this algorithm. There are many straightforward ways a node can use (up to) $\log N$ bits to uniformly select a value from a set containing no more than N values.

And for the case of an empty set, we define by default $adv_r(\emptyset) = 0$. Fix $T'_u(r) = T_u(r) \setminus T_v(r)$ and $T'_v(r) = T_v(r) \setminus T_u(r)$. Let $T'_{u,v}(r) = T_u(r) \cap T_v(r)$. It follows:

$$\begin{aligned} b_u(r) &= adv_r(T'_u(r)) + adv_r(T'_{u,v}(r)) \pmod 2 \\ b_v(r) &= adv_r(T'_v(r)) + adv_r(T'_{u,v}(r)) \pmod 2 \end{aligned}$$

Given the above observation, we note that $b_u(r) = b_v(r)$ if and only if $adv_r(T'_u(r)) = adv_r(T'_v(r))$. By definition, $T'_u(r)$ and $T'_v(r)$ have no values in common and at least one of these sets is non-empty. The bits used in these sums are all therefore pairwise independent and generated uniformly. The probability that both these sums are equal is exactly $1/2$, and therefore so is the complementary probability of inequality. \square

We next define the following useful potential function that captures the amount of information spreading still required in the network to solve gossip after a given round:

$$\forall r \geq 1 : \phi(r) = \sum_{u \in V} (k - |T_u(r)|).$$

Notice that this function is non-increasing (as nodes never unlearn a token), and once the function evaluates to 0, there is no more information to spread and therefore gossip is solved. We now leverage the definition of potential function ϕ from above to define what it means for a round to be *good* with respect to making progress with the gossip problem:

Definition 5.3. *We say a given round $r \geq 1$ is good if and only if one of the following two properties is true: (1) $\phi(r) = 0$; or (2) $\phi(r+1) < \phi(r)$.*

The following result leverages Lemma 5.2 to formalize the key property that each round of our algorithm has a reasonable probability of being good by our above definition.

Lemma 5.4. *For every round r , $1 \leq r \leq cN^2$, the probability that round r is good is at least $1/4$.*

Proof. There are two cases depending on the value of $\phi(r)$. If $\phi(r) = 0$, then by definition this round is good. Else if $\phi(r) > 0$, we must consider the probability that at least one node learns a new token in this round. To do so, fix some token t that is not known by all n nodes at the beginning of r (such a token must exist by the assumption that $\phi(r) > 0$). Let S be the nodes that know t . Because we assume the network topology is connected in each round, there must be an edge during round r between a node $u \in S$ and a node $v \in V \setminus S$.

Because $t \in T_u(r)$ and $t \notin T_v(r)$, we know $T_u(r) \neq T_v(r)$. By Lemma 5.2, the probability that $b_u(r) \neq b_v(r)$ is $1/2$. Assume this event occurs. Also assume $b_u(r) = 1$ and $b_v(r) = 0$ (the opposite case is symmetric). By the definition of the algorithm, u will attempt to send a proposal in this round and it has at least one neighbor to choose from to receive this proposal. Let v' be the neighbor u chooses. Whether or not $v' = v$, we know that v' advertised 0 in this round. By Lemma 5.2, it follows that v' has a different token set than u in this round. Indeed, this must be true of v' and *any* node that sends it a proposal in this round.

Now that we have established that v' receives at least one proposal, we know v' will form a connection this round. As we just noted, this connection will be with a node u' such that $T_{u'}(r) \neq T_{v'}(r)$. Therefore, with high probability in n , the transfer subroutine will successfully identify a missing token to transfer between u' and v' —reducing ϕ .

We have just shown that for r to be good in the case where $\phi(r) > 0$, it is sufficient that the following two events occur: (1) $b_u(r) \neq b_v(r)$; and (2) the transfer subroutine between u' and v' succeeds. The first occurs with probability $1/2$, and the second with high probability, which is at least $1/2$ for $n > 1$ (which must be true if $\phi(r) > 0$). Both events occur, therefore, with probability at least $1/4$ —as required. \square

We can now leverage Lemma 5.4 to prove Theorem 5.1. The key argument in the following is that $\phi(1) \leq kn$, therefore kn good rounds are sufficient to solve the gossip problem. With high probability, $T = \Theta(kn)$ total rounds is sufficient to achieve this goal—*assuming* that \hat{r} is long enough to supply random bits for T rounds. To assure this holds we fix the constant c in the definition of \hat{r} to be at least the constant identified in the analysis below for the definition of T (which turns out to be 32).

Formalizing this intuition, however, requires some care in dealing with potential dependencies between different rounds with respect to their goodness.

Proof (of Theorem 5.1). The potential function ϕ measures the number of missing values over the n total nodes. Each node can miss at most k values. Therefore: $\phi(1) \leq kn$. Because ϕ is non-increasing, it is sufficient to ask how many rounds are required to ensure kn good rounds with high probability. Here we show that $32kn$ rounds are more than sufficient. If we fix the constant c used in the definition of \hat{r} to 32, therefore, it follows that \hat{r} is sufficiently long to supply random bits for all $32kn$ rounds needed for high probability termination.

Continuing with the proof, let X_r , for each round $r \geq 1$, be the random indicator variable that evaluates to 1 if and only if round r is good. Let Y_t , for some round count $t \geq 1$, be defined as:

$$Y_t = \sum_{r=1}^t X_r.$$

The Y_t variable, in other words, measures the number of good rounds in the first t rounds. By Lemma 5.4, we know $E(Y_t) \geq t/4$. Therefore, in expectation, $4kn$ rounds are sufficient to achieve kn good rounds. To achieve high probability, however, we cannot simply concentrate on this expectation as there may be dependencies between different X variables (e.g., the outcome in one round might increase the probability that the next is good).

Because Lemma 5.4 establishes a lower bound on this probability that holds regardless of the execution history, we can deploy a stochastic dominance argument to achieve our needed result. In more detail, let \hat{X}_r , for each $r \geq 0$, be the trivial random indicator variable that evaluates to 1 with independent probability $1/4$. Let $\hat{Y}_t = \sum_{r=1}^t \hat{X}_r$. Clearly, $E(\hat{Y}_t) = t/4$. Because the \hat{X} variables are pairwise independent, we can concentrate on this expectation. For example, fix $t = 32kn$. Applying the Chernoff bound from Section 2 (Theorem 2.2) with $\delta = 1/2$ and $\mu = E(\hat{Y}_t) = t/4 = 8kn$, it follows:

$$\Pr(\hat{Y}_t \leq 4kn) \leq e^{-\frac{8kn}{8}} \leq e^{-n} < 1/n.$$

That is, for this particular value of $t \in \Theta(kn)$, the probability that \hat{Y}_t is less than kn is small in n . We now note that for each $r \geq 1$, X_r stochastically dominates \hat{X}_r . It follows that our above bound on \hat{Y}_t holds for Y_t as well—which is sufficient to conclude the proof. \square

5.2 Eliminating the Shared Randomness Assumption

Here we discuss how to remove the assumption of shared randomness. In more detail, we describe SimSharedBit, a variation of SharedBit that does not use shared randomness. We emphasize that this new algorithm is existential instead of constructive. Formally, it depends on a small set of bit strings, called \mathcal{R}' , that we prove exists but do not explicitly construct. Accordingly, our main theorem statement below references the *existence* of a string set \mathcal{R}' for which SimSharedBit is an efficient solution.

The SimSharedBit algorithm adds an additive cost of $\tilde{O}(\Delta^{1/\tau}/\alpha)$ rounds to the existing time complexity of SharedBit. For most combinations of Δ , τ , and α , and k , this additive cost is swamped by the $O(kn)$ time

complexity of SharedBit. For the worst-case values of these parameters, this extra cost can make SimSharedBit up to a factor of n slower than SharedBit (e.g., when $k = 1$, $\alpha = 1/n$, $\Delta = n - 1$, and $\tau = 1$).

Strategy Summary. The high-level strategy for SimSharedBit is to first elect a leader that disseminates a *seed* string that can be used to generate sufficient randomness to run SharedBit. Notice, the number of shared bits required by SharedBit is much too large to be efficiently disseminated (our model restricts connections to deliver $\text{polylog}(N)$ bits per round, while SharedBit requires $\Omega(N^3)$ shared bits). The seed selected and disseminated by the leader, by contrast, is small enough to be fully transmitted over a connection in a single round. To prove that there exists a randomness generator that can extract sufficient randomness for our purpose from seeds of this small size, we adapt the technical details of Newman’s Theorem (e.g., [21]) from the simpler world of two-party communication to the more complicated world of n parties on a distributed and changing network topology. In more detail, we prove the existence of a multiset \mathcal{R}' , containing only $\text{poly}(N)$ bit strings of the length required for SharedBit, that is *sufficiently* random to guarantee that if a leader chooses \hat{r} uniformly from \mathcal{R}' , the SharedBit algorithm using shared randomness \hat{r} is still likely to solve gossip efficiently. Because \mathcal{R}' contains only $\text{poly}(N)$ strings, the leader can identify the string it selected using only $\text{polylog}(N)$ bits (this selection is the *seed* it disseminates)—enabling efficient dissemination of this information. The existential nature of SimSharedBit is entirely encapsulated in the existence of this set \mathcal{R}' .

Below we begin by describing the guarantees of the leader election primitive we will leverage in the SimSharedBit algorithm. We then describe the operation of SimSharedBit before proceeding with its analysis.

Leader Election. To elect a leader we can deploy the BitConvergence leader algorithm described in our recent study of leader election in the mobile telephone model [22]. When run in a network with expansion α , stability factor $\tau \geq 1$, and maximum degree Δ , this algorithm guarantees with high probability in N to solve leader election in $O((1/\alpha)\Delta^{1/\tau}\text{polylog}(N))$ rounds. We emphasize that the algorithm does not require advance knowledge of α , Δ , or τ —its time complexity adapts to the network in which it is executed.

To provide slightly more detail about this algorithm, in each round, each node identifies a single identifier to be its candidate leader for that round. To “solve leader election” means that eventually all candidate leaders in the network have permanently stabilized to the same identifier. As noted in [22], a trivial extension to the algorithm allows each node to also generate a *payload* consisting of $\text{polylog}(N)$ bits that follows its identifier. Each node now maintains a variable for its current candidate leader and a variable for that candidate’s payload. We will leverage this payload in SimSharedBit to carry a pointer to a \hat{r} value from \mathcal{R}' . Finally, we note that BitConvergence also maintains the useful property that the eventual leader will be the node with the *smallest* identifier of all participating nodes. This simplifies our analysis.

The SimSharedBit Gossip Algorithm. We are now ready to describe the SimSharedBit gossip algorithm. This new gossip algorithm interleaves the BitConvergence leader election algorithm described above with the logic from SharedBit gossip. In more detail, we will prove below the existence of a multiset \mathcal{R}' , containing $\text{poly}(N)$ bit strings, that is “sufficiently random” (a concept we will formalize soon) that it is sufficient for the nodes in the network to agree on a shared string \hat{r} sampled from \mathcal{R}' , instead of from the space of all possible strings of the needed length.

In more detail, at the beginning of the execution, each node selects its own string from \mathcal{R}' with uniform randomness. Assume we have fixed in advance a deterministic unique labeling of the $\text{poly}(N)$ strings in \mathcal{R}' with the values $1, 2, \dots, |\mathcal{R}'|$. Each node can therefore refer to the string it selected with its label. Following the standard conventions of pseudorandomness, we call this label the *seed* for the string. Notice, each seed can be described with only $\text{polylog}(N)$ bits. We take advantage of this small size by having each node run the leader election algorithm summarized above with this string stored in its payload. Therefore, once we elect a leader, all nodes also know its seed.

To interleave gossip and leader election we will treat even and odd rounds differently. In even rounds, nodes execute the BitConvergence leader election algorithm described above, using their seed as their payload. In odd rounds, nodes execute the SharedBit gossip algorithm. In each odd round, each node uses as the

shared string \hat{r} whatever string from \mathcal{R}' is pointed to by the seed in their current candidate leader's payload. In defining \mathcal{R}' below, we will fix the length of strings in this set to be slightly longer than the strings used by SharedBit, so as to capture the extra rounds required for the network to converge on a single string (the rounds before this point are potentially wasted with respect to making gossip progress).

Proving the Existence of a Sufficiently Random \mathcal{R}' . To prove SimSharedBit solves gossip efficiently with high probability, we must prove that a shared string sampled uniformly from \mathcal{R}' is sufficiently random that the SharedBit logic executed in odd rounds will still solve gossip with high probability.

To do so, we begin by establishing some preliminary assumptions and definitions. First, we note that the string \hat{r} used by SharedBit consists of $t_{SB} = cN^2$ groups consisting of N bundles that in turn each contain $t_b = (\lceil \log N \rceil + 1)$ bits. The algorithm consumes bits from one group per round, and the analysis of SharedBit requires at most t_{SB} rounds worth of shared randomness to terminate with high probability.

For SimSharedBit, we will need to extend this length to account for the early rounds in the execution when leader election has not yet converged, and therefore we cannot yet guarantee useful progress for the gossip logic executing in the odd rounds. For the worst case values of α , τ , and n , BitConvergence requires no more than $t_{BC} = O(N^2 \text{polylog}(N))$ rounds to converge. Therefore we extend the length of shared bit strings to consist of $t_{SSB} = t_{SB} + t_{BC} = O(N^2 \text{polylog}(N))$ groups. This ensures that after leader election converges we still have at least the full t_{SB} rounds of randomness needed for the analysis of SharedBit to apply. At the risk of slightly overloading previous notation, we will use $\mathcal{R} = \{0, 1\}^{t_{SSB} \cdot N \cdot t_b}$ to refer to the set of all bit strings of length $t_{SSB} \cdot N \cdot t_b$ —the maximum size shared string needed to give nodes time to converge to a leader and then subsequently solve gossip with the leader's shared string. The shared strings used in SimSharedBit come from \mathcal{R} .

Next, for a given network size $n > 1$, let $\mathbb{G}(n)$ be the set containing every t_{SB} -round dynamic graph defined over n nodes. That is, if we run our algorithm for t_{SB} rounds in a network of size n , it will be executed in some dynamic graph $\mathcal{G} \in \mathbb{G}(n)$. Let $\mathcal{A}(n)$ be the set containing every assignment of token sets to the n nodes in a network of size n . We define “assignment” to capture two key pieces of information: (1) which nodes in the network started with a token; and (2) which of these tokens does each node know at the moment. Formally, a given $A \in \mathcal{A}(n)$ can be described as a function from $[n]$ to 2^n .⁶

For each network size $n \in [2, N]$, round $\ell \in [1, t_{BC}]$, dynamic graph $\mathcal{G} \in \mathbb{G}(n)$, token assignment $A \in \mathcal{A}(n)$, and shared bit string $\hat{r} \in \mathcal{R}$: let $Z(n, \ell, \mathcal{G}, A, \hat{r})$ be the random indicator variable that evaluates to 0 if SharedBit solves gossip when run in a network of size n , starting with token assignment A , and executing for t_{SB} rounds in dynamic graph \mathcal{G} , using the shared random bits from groups ℓ to $\ell + t_{SB}$ in \hat{r} . It otherwise evaluates to 1. (In the evaluation of Z , assume that the probabilistic token transfer subroutine used by SharedBit always works correctly.) Notice, we are using 0 to indicate a positive outcome (gossip works), and a 1 to indicate a negative outcome (gossip failed).

In other words, $Z(n, \ell, \mathcal{G}, A, \hat{r})$ answers the following question (with 0 indicating *yes*) :

If we assume we are in a network of size n , and that leader election converges to a single leader at round ℓ , and this leader points toward shared string \hat{r} , and that at this point the tokens in the network are spread according to A : will the SharedBit logic solve gossip sometime in the next t_{SB} rounds, using the corresponding bits from \hat{r} , assuming the graph evolves as \mathcal{G} during this round interval?

Our analysis of SharedBit tell us that if we select \hat{r} uniformly from \mathcal{R} , with high probability: $Z(n, \ell, \mathcal{G}, A, \hat{r}) = 0$. Our goal is to prove that there exists a multiset \mathcal{R}' , made up of values from \mathcal{R} , such that \mathcal{R}' only contains $\text{poly}(N)$ strings, and yet if we select \hat{r} uniformly from \mathcal{R}' , the probability $Z(n, \ell, \mathcal{G}, A, \hat{r}) = 0$ remains high.

⁶This function maps each of the n nodes to some subset of $[1, n]$ indicating the tokens that node knows. The set of nodes that started with a token according to this assignment is the set of nodes that have a token show up somewhere in the assignment function's range.

In particular, if ϵ is an upper bound on the small failure probability of SharedBit gossip when run in a setting with shared randomness, then we show the probability that Z evaluates to 1 when drawing \hat{r} from our multiset \mathcal{R}' is at most only a constant factor larger. We formalize this goal with the following lemma. We emphasize that this setup (analyzing the probability that Z evaluates to 1 with our reduced \mathcal{R}') comes from the proof of Newman's Theorem. We are generalizing this approach, however, to account for multiple nodes operating on a dynamic graph starting from an arbitrary round within a larger interval, with an arbitrary distribution of gossip tokens:

Lemma 5.5. *There exists a multiset \mathcal{R}' of size $N^{\Theta(1)}$ containing values from \mathcal{R} , such that for every $n \in [2, N]$, $\ell \in [1, t_{BC}]$, $\mathcal{G} \in \mathbb{G}(n)$ and $A \in \mathcal{A}(n)$, it follows:*

$$\Pr_{\hat{r} \leftarrow \mathcal{R}'} (Z(n, \ell, \mathcal{G}, A, \hat{r}) = 1) < 2\epsilon,$$

where $\epsilon = N^{-c}$ (for some constant $c \geq 1$) is an upper bound on the failure probability of SharedBit gossip when executed with shared randomness.

Proof. Fix some network size $n \in [2, N]$, leader election termination round $\ell \in [1, t_{BC}]$, $\mathcal{G} \in \mathbb{G}(n)$ and $A \in \mathcal{A}(n)$. Consider an experiment in which we uniformly select t values r_1, r_2, \dots, r_t from \mathcal{R} (with replacement), where $t > 0$ is a value defined with respect to N that we fix below. Let X_i be the random indicator variable defined as $X_i = Z(n, \ell, \mathcal{G}, A, r_i)$. That is, $X_i = 0$ if SharedBit solves gossip using the relevant bits in r_i in \mathcal{G} starting with assignment A . By Theorem 5.1 and our definition of t_{SB} (which captures the worst case time complexity from this theorem), we know $X_i = 0$ with probability at least $1 - \epsilon$. Therefore:

$$E(X_i) = 0 \cdot \Pr(X_i = 0) + 1 \cdot \Pr(X_i = 1) \leq \epsilon.$$

Note that these random variables X_1, X_2, \dots, X_t are i.i.d. as they are each determined by a random string selected with uniform and independent randomness with replacement from a common set. It follows that we can apply a Chernoff-Hoeffding bound (Theorem 2.4 from Section 2) to X_1, X_2, \dots, X_t to prove that their average value is unlikely to deviate too much from the expected average. In more detail, let $\mu = E(X_i)$. This bound tells us that for any $\delta > 0$:

$$\Pr \left(\frac{1}{t} \sum_{i=1}^t X_i \geq \mu + \delta \right) \leq e^{-2\delta^2 t}.$$

Fix $\delta = \epsilon$ and $t = N^\beta / \epsilon^2$, for a constant $\beta \geq 1$ we will define below. We say for our fixed choice of n , \mathcal{G} and A , that a given selection of t strings from \mathcal{R} is *bad* if $\frac{1}{t} \sum_{i=1}^t X_i \geq p = 2\epsilon$. For our fixed values of δ and ϵ , and our above bound, we know our random choice of strings is bad with probability no more than $e^{-2N^\beta} < 2^{-N^\beta}$. Put another way, for a fixed network size, leader election termination round, dynamic graph and token assignment, we are very unlikely to have made a bad selection of strings.

Now we consider other values for our parameters. We know there are no more than N choices for n and $c'N^2 \text{polylog}(N)$ choices for ℓ , for some constant $c' \geq 1$. For a given n , we can bound $\mathbb{G}(n)$ as

$$|\mathbb{G}(n)| < (2^{n^2})^{t_{SB}} = 2^{n^2 \cdot t_{SB}} \leq 2^{N^\gamma},$$

for some small constant $\gamma \approx 4$. And to bound $\mathcal{A}(n)$, we note:

$$|\mathcal{A}(n)| \leq (2^n)^n \leq 2^{n^2} \leq 2^{N^2}.$$

The total number of combinations of n , ℓ , \mathcal{G} and A values, therefore, is upper bounded by:

$$\begin{aligned}
N \cdot (c' N^2 \text{polylog}(N)) \cdot 2^{N^\gamma} \cdot 2^{N^2} &\leq c' \cdot 2^{\log N^3 + \log(\text{polylog}(N)) + N^\gamma + N^2} \\
&\leq 2^{N^\gamma \cdot c''}
\end{aligned}$$

for some constant $c'' \geq 1$. Given this upper bound value, we fix the constant β used in the definition of t to be some constant strictly greater than $c'' \cdot \gamma$ (say, $\lceil c'' \cdot \gamma + 1 \rceil$).

We now apply the probabilistic method to prove the existence of a selection of t values from \mathcal{R} that is *not* bad for any of the possible combinations of network sizes, leader election termination points, graphs and token assignments. To do, note that the probability of a given selection being bad for a fixed set of parameters was shown above to be less than 2^{-N^β} . By applying a union bound over the less than $2^{N^{c'' \cdot \gamma}}$ combinations of parameters, the probability that there exists *at least* one such combination for which our selection is bad is less than: $(2^{N^{c'' \cdot \gamma}}) \cdot (2^{-N^\beta}) < 1$.

It follows that there exists at least one collection of t values from \mathcal{R} that is not bad for every combination of the relevant parameters. Let us call this multiset of t values \mathcal{R}' .

The definition of being not bad for a given graph and assignment is that: $\frac{1}{t} \sum_{i=1}^t X_i \leq 2\epsilon$. It follows that $\sum_{i=1}^t X_i \leq 2t\epsilon$. From this it follows that at most a 2ϵ fraction of the X_i values evaluate to 1. Therefore, if we uniformly sample a string r_i from \mathcal{R}' , the probability that $X_i = 0$ is at least $1 - 2\epsilon$, as required by the lemma statement.

To conclude the proof, we must show that $|\mathcal{R}'| = t$ is in $\text{poly}(N)$. We earlier fixed: $t = N^\beta / \epsilon^2$, where $\beta = \Theta(1)$ and $\epsilon = N^{-c}$ for a constant $c \geq 1$. It follows that $t = N^{\beta+2c} = N^{\Theta(1)}$. \square

We now leverage Lemma 5.5 to prove our main theorem concerning SimSharedBit:

Theorem 5.6. *There exists a bit string multiset \mathcal{R}' of size $N^{\Theta(1)}$, such that the SimSharedBit gossip algorithm using this \mathcal{R}' as its source of simulated shared bit strings solves the gossip problem in $O(kn + (1/\alpha)\Delta^{1/\tau} \log^6 N)$ rounds when executed with tag length $b = 1$ in a network with stability $\tau \geq 1$.*

Proof. Fix the multiset \mathcal{R}' proved to exist in Lemma 5.5. We now study the performance of SimSharedBit using this multiset as the source of shared random strings selected by leader candidates.

First, we note that by Theorem 5.1, we know that SharedBit gossip solves gossip in $O(kn)$ rounds with high probability. In [22], we proved that BitConvergence leader election solves leader election in $O((1/\alpha)\Delta^{1/\tau} \log^6 N)$ rounds with high probability. In Section 3, we proved that the transfer routine succeeds with high probability. By a union bound, we can therefore assume that with (slightly less) high probability the transfer routine works every time it is called in a $\text{poly}(N)$ round execution.

Let ϵ be the smallest of these three small failure probabilities. In a given execution of SimSharedBit, it follows (by a union bound) that the probability that the transfer routine fails at least once, or BitConvergence fails to elect a leader in the provided time bound, is less than 2ϵ .

Assume neither of these two bad events occur. We now study the probability that SimSharedBit, running with a \hat{r} selected uniformly by the node with the smallest ID from the \mathcal{R}' , starting from the round right after leader election succeeds, and runnings on the given dynamic graph for the execution. By Lemma 5.5, the probability that SimSharedBit fails to solve gossip is also less than 2ϵ .

A final union bound on these two failure probabilities establishes that the probability SimSharedBit gossip fails is less than 4ϵ , and therefore it succeeds with probability at last $1 - 4\epsilon$. So long as we set the constant factors in the time complexity of SharedBit, BitConvergence, and the transfer routine, to ensure that $\epsilon \leq \frac{1}{4N}$, SimSharedBit succeeds with high probability. \square

6 Gossip with $b = 1$ and $\tau = \infty$

Here we describe and analyze a gossip algorithm that requires only $\tilde{O}(k/\alpha)$ rounds when executed with $b = 1$ and a stable network (where \tilde{O} hides $\text{polylog}(N)$ factors). Because $\Omega(k)$ is a trivial lower bound for gossip k messages in our model, this algorithm is optimal for larger α . Recall that for $\tau \geq 1$ our best solution required $O(kn)$ rounds. This algorithm matches this time for the worst-case α values but then improves over it as α increases. For constant α , this algorithm performs a factor of n faster (ignoring log factors). These results indicate that network stability is valuable from a gossip algorithm perspective. Notice, for the sake of presentation clarity, the algorithm analysis that follows does not attempt to optimize the polylogarithmic factors multiplied to the leading k/α term.

Discussion: Crowded Bins We call this algorithm CrowdedBin gossip. This name comes from a core behavior in the algorithm in which nodes toss their tokens into a fixed number of bins corresponding to their current estimate \hat{k} of k (the number of tokens in the network). Nodes do not know k in advance. Determining this value is crucial to enabling efficient parallel dissemination of their tokens. Leveraging a new balls-in-bins analysis, we upper bound the number of tokens in any given bin *if* the estimate \hat{k} is sufficiently large. The nodes therefore search for crowded bins as evidence that they need a larger estimate of k . This mechanism provides a way to check that a current guess \hat{k} is too small while only paying a time complexity price relative to \hat{k} (as there are only \hat{k} bins required to check for crowding). Because the sequence of guesses we try are geometrically increasing, the cost of checking estimates smaller than k will sum up to $\tilde{O}(k)$.

Discussion: Spreading Bits versus Spreading Tokens. We also emphasize that the CrowdedBin algorithm makes a clear distinction between propagating information using the advertising bits and propagating the tokens themselves (which are treated as black boxes, potentially large in size, that require a pairwise connection for transfer). Combining the stability of the network with each node’s ability to advertise a bit to *all* its neighbors in each round, nodes first attempt to stabilize to a consistent and accurate estimate of k , and a consistent set of *tags* describing the network’s tokens. Once stabilized, this information can then support the efficient spreading of the tokens, link by link, to the whole network.

The PPUSH Rumor Spreading Strategy. The CrowdedBin algorithm uses a simple rumor spreading strategy called PPUSH as a subroutine to help spread tokens once the network has stabilized. This algorithm was introduced in our earlier study of rumor spreading in the mobile telephone model [11]. PPUSH assumes a subset of nodes start with a common rumor m , and the goal is to spread m to all nodes. It requires $b \geq 1$.

In more detail, the strategy PPUSH works as follows: (1) at the beginning of each round, if a node knows m (i.e., it is *informed*), it advertises bit 1, otherwise if it does not know m (i.e., it is *uninformed*), it advertises bit 0; (2) each informed node that has at least one uninformed neighbor in this round, chooses an uninformed neighbor with uniform randomness and attempts to form a connection to spread the rumor. In [11], we proved the following key result about the performance of PPUSH:

Theorem 6.1 (Adapted from [11]). *With high probability in N : PPUSH succeeds in spreading the rumor to all nodes in $O(\log^4 N/\alpha)$ rounds when executed in the mobile telephone model with $b \geq 1$, $\tau = \infty$, and a topology graph with expansion α .*

We will leverage this theorem in our analysis of our gossip algorithm. We also use the following useful property proved in [11] which relates network diameter to expansion:⁷

Theorem 6.2 (Adapted from [11]). *Fix a connected graph with n nodes, expansion α , and diameter D . It follows that $D = O(\log n/\alpha)$.*

⁷The actual result we proved in [11] is that it is always possible to spread a rumor in $O(\log n/\alpha)$ rounds in the mobile telephone model in a graph with expansion α . The rumor spreading time in a given network can never be smaller than the network diameter, which provides a trivial lower bound on the problem.

6.1 The CrowdedBin Gossip Algorithm

We divide our description of this analysis into several named parts to clarify its presentation. In the following, we assume each node $u \in V$ identifies itself with a *tag* t_u chosen uniformly from the space $\{1, 2, \dots, N^\beta\}$, where $\beta \geq 2$ is constant we fix in our analysis. Let $\ell = \beta \log N$ be the number of bits needed to describe a tag. To simplify notation, we assume in the following that N is a power of 2.

Parallelizing Instances. Nodes do not know in advance the value of k (the number of tokens in the system). They consider $\log N$ estimates of k : $k_1, k_2, \dots, k_{\log N}$, where each $k_i = 2^i$. The nodes run in parallel a separate gossip *instance* for each estimate. We use the notation *instance* i to refer to the instance corresponding to estimate k_i . In order to run $\log N$ instances in parallel, each node uses $\log N$ rounds to simulate one round each of the $\log N$ instances. That is, nodes divide rounds into *simulation groups* consisting of $\log N$ rounds. Round j of simulation group i is used to simulate round i of instance j .

Instance Schedules. Each instance i groups its rounds into *blocks* containing $\ell + \log N$ rounds each. It then groups these blocks into *bins* containing $\gamma \log N$ blocks each, where $\gamma > 1$ is a constant we fix in our analysis below. Finally, it groups the bins into *phases* consisting of k_i bins each. In other words, the schedule for instance i is made up of phases, where each phase has k_i bins, which are each made up of $\gamma \log N$ blocks, which each contain $\ell + \log N$ rounds: adding to a total of $\gamma(\beta + 1)k_i \log^2 N$ total rounds per phase.

Initialization. Each node $u \in V$ that begins an execution of the CrowdedBin algorithm with a gossip token, independently selects a bin for its token for each of the $\log N$ instances. That is, for each instance i , u selects a bin $b_u(i)$ with uniform independent randomness from $\{1, 2, \dots, k_i\}$. Each node u also maintains, for each instance i , and each bin j for this instance, a set $T_u(i, j)$ containing the tags it has seen so far for tokens in bin j in instance i . For each instance i , if node u has a token it initializes $T_u(i, b_u(i)) = \{t_u\}$ (i.e., it places its own tag in the bin it selected for that instance). Node u also maintains a set Q_u containing the tokens it has received so far, where each token in Q_u is also labeled with its tag. Finally, each node u maintains a variable est_u , initialized to 1, which describes the current instance node u is participating in.

Participation. Each node will only participate in a single instance at a time, and it will only participate in complete phases of an instance. In more detail, if some instance i starts a new phase in round r , and some node u has $est_u = i$ at the start of round r , node u is now committed to participate in this full phase of instance i . As we will detail, its estimate cannot change again until this phase completes.

To participate in a phase of instance i , node u does the following. First, for each bin j , $1 \leq j \leq k_i$, u orders the tags in $T_u(i, j)$ (if any) in increasing order. It will use the first ℓ rounds of the first block to spell out the smallest such tag, bit by bit, using its advertising bits (here the assumption that $b \geq 1$ is needed). It will then use the first ℓ rounds of the second block to spell out the second smallest tag, and so on. There are $\gamma \log N$ total blocks in this bin. If u knows more than this many tags for this bin, it transmits only the first $\gamma \log N$. Node u transmits all 0's during the blocks in this bin for which it has no tags to advertise (here is where we use the assumption that the smallest possible tag is 1—preventing a block of all 0's from being mistaken for a tag.)

During the rounds dedicated to bin j , node u also collects the bits advertised by its neighbors in each block. If it learns of a tag t_v that is not currently in $T_u(i, j)$, it will put it aside and then add it to this set once the rounds dedicated to bin j in this phase conclude.

We have only so far described what node u does during the first ℓ rounds for each block in our fixed instance j . During the remaining $\log N$ rounds in these blocks, u will attempt to disseminate the actual tokens corresponding to the tags advertised (here we emphasize the difference between spelling out the bits of a tag using advertising bits and actually transmitting a token, which requires two nodes to form a connection). In more detail, u executes the PPUSH rumor spreading strategy discussed above during the last $\log N$ rounds of each block in the current bin. In more detail, for a given block h in this bin, if u advertised tag t in the first ℓ rounds of this block, and u actually has the token corresponding to tag t in Q_u , it executes PPUSH in the

remaining rounds of this block using this token as the rumor and advertising 1 (i.e., it runs PPUSH with the status of an already informed node). Otherwise, node u runs PPUSH advertising 0 (i.e., it runs the PPUSH as an uninformed node).

Increasing Size Estimates. A core behavior in this algorithm is how nodes upgrade their current estimate of the value k (stored in est_u for each node u). As described above, each node initializes their estimate to 1. As described below, these estimates can only grow during an execution. We call an increase in this estimate at a given node an *upgrade*. There are two events that trigger an upgrade at a given node u .

The first event is that node u sees “activity” on an instance $i' > est_u$, where est_u is its current estimate. The term “activity” in this context means seeing a 1-bit advertised in an instance i' round. If this event occurs, then u knows that some other node has already increased its estimate beyond est_u , so u should upgrade its estimate as well. The second event is that node u fills a bin in its current estimate. That is, there is some bin j such that $|T(est_u, j)| \geq \gamma \log N$. We call this event a *crowded bin*, and u can use this as evidence that est_u does not have enough bins for the number of tags in the system and therefore est_u is too small of an estimate for k . If this event occurs, u will increase est_u by 1 (unless est_u is already at its maximum value in which case it will remain unchanged.).

Recall, as specified above, that if a node u increases its estimate est_u to a new value, it will complete the phase of whatever instance it was participating in before switching to the new estimate moving forward. This restriction simplifies the analysis that follows.

6.2 Analysis

In the following analysis, let D be the diameter of the fixed underlying topology graph. Some of intermediate results below will reference D . Our final result, however, will be expressed only with respect to α to maintain comparability to earlier results defined for non-stable networks in which D is not well-defined.

At the beginning of an execution each node randomly assigns a tag from $\{1, 2, \dots, N^\beta\}$ to its token, and then randomly assigns the token to a bin in each of the $\log N$ instances. We call the global collection of these assignments for a given execution a *configuration*. Fix a configuration. We call a given instance i of this configuration, $1 \leq i \leq \log N$, *crowded*, if the configuration has an instance i bin with at least $\gamma \log N$ unique tags assigned to it. The *target* instance for our fixed configuration is the smallest instance i that is *not* crowded. If every instance is crowded, then we say the *target* instance is *undefined*. We begin our analysis by defining what it means for a configuration to be *good* with respect to these terms:

Definition 6.3. *A configuration is good if and only if it satisfies the following two properties: (1) every token is assigned a unique tag; and (2) the target instance i is defined, and $k_i \leq 2k$.*

A direct corollary of the above definition is that if a configuration is good, and i is the target, then $k_i > k/(\gamma \log N)$. We now bound the probability that the nodes generate a good configuration. We will show that increasing the constant β , used to define the space $\{1, 2, \dots, N^\beta\}$ from which tags are drawn, and the constant γ , used to define the number of blocks per bin, increases the high probability that a configuration is good. To make this argument we begin by proving a non-standard balls-in-bins argument that will prove useful to our specific algorithm’s behavior.

Lemma 6.4. *Fix some constant $\gamma \geq 9$. Assume k balls, $1 \leq k \leq N$, are thrown into $k' \geq k$ bins with independent and uniform randomness. The probability that at least one bin has at least $\gamma \log N$ balls, is less than $1/N^{(\gamma/3)-2}$.*

Proof. Label the balls $1, 2, \dots, k$ and the bins $1, 2, \dots, k'$. Let b_1 be bin in which ball 1 is thrown. We now calculate the expected number of other balls to land in b_1 . To do so, for each ball $i > 1$, let X_1 be the random indicator variable that evaluates to 1 if i lands in b_1 and otherwise evaluates to 0. Let $Y_{b_1} = \sum_{1 < i \leq k} X_i$

be the total number of additional balls to land in b_1 . By linearity of expectation and the observation that $E(X_i) = 1/k' \leq 1/k$, it follows that $\mu = E(Y_{b_1}) < 1$.

By definition of the process, X_i and X_j are independent for $i \neq j$. We can therefore apply an upper bound form of a Chernoff Bound (Theorem 2.4) to concentrate near this expectation. In particular, define $\delta = (\gamma \log N - 2)/\mu$. Notice, $\delta > (\gamma \log N - 2) > 1$. We can therefore apply Theorem 2.4 to $Y = Y_{b_1}$, and our above definitions of δ and μ . It follows that:

$$\begin{aligned}
\Pr(Y_{b_1} \geq (1 + \delta)\mu) &\leq \exp\{-(\gamma \log N - 2)/3\} \\
&= \exp\{-((\gamma/3) \log N - 2/3)\} \\
&= \exp\{-((\gamma/3) \ln N \log e - 2/3)\} \\
&< \frac{e^{2/3}}{e^{(\gamma/3) \ln N}} \\
&< 2/N^{\gamma/3} \\
&\leq 1/N^{\gamma/3-1}
\end{aligned}$$

Notice, $(1 + \delta)\mu = \mu + (\gamma \log N - 2)$, and $\mu = 1/k' \in (0, 1)$. Therefore, we can interpret the above bound saying that the probability that b_1 has at least $\gamma \log N - 1$ extra balls is less than $1/N^{\gamma/3-1}$. When we add in ball 1, which by definition is also in b_1 , we get that the probability that b_1 has at least $\gamma \log N$ balls is also less than $1/N^{\gamma/3-1}$. By symmetry, the same result holds for b_2 through b_k as well. There are dependencies between the outcomes in different bins, but we can dispatch this issue by applying a union bound over the $k \leq N$ occupied bins, which provides that the probability *at least* one bins has more than $\gamma \log N$ balls is less than $N/N^{(\gamma/3)-1} = 1/N^{(\gamma/3)-2}$. \square

Lemma 6.5. *Fix some constant $c \geq 1$. For a tag space constant $\beta \geq c+3$, and a bin size constant $\gamma \geq 3c+9$, the nodes generate a good configuration with probability at least $1 - 1/N^c$.*

Proof. There are two parts to the definition of *good*. The first requires each tag to be unique. The probability that there is at least one collision among the tag choices, given that no more than N tags are drawn from N^β options, can be loosely upper bounded as $1/N^{\beta-2}$. If we define $\beta = c + 3$ then this failure probability is less than $1/N^{c+1}$.

The second part of the definition requires that the target instance is defined and it is not too large compared to the actual number of tokens, k . Let $\hat{i} = \operatorname{argmin}_{1 \leq i \leq \log N} \{k \leq k_i\}$. That is, $k_{\hat{i}}$ is the smallest estimate of k considered by our algorithm that is at least as large as k . Because our estimates grow by a factor of 2, we know that $k_{\hat{i}} < 2k$. If we can show that $k_{\hat{i}}$ is not crowded, therefore, it will follow that the target instance i for this configuration is defined, and $i \leq \hat{i}$: which is sufficient to satisfy the second part of the definition of *good*.

To make this argument, we can treat the selection of bins for each token in instance \hat{i} as a balls in bins problem. We therefore apply Lemma 6.4 to k and $k' = k_{\hat{i}}$, which tells us that for any constant $\gamma \geq 9$, the probability that instance \hat{i} crowded is less than $1/N^{(\gamma/3)-2}$. If we set our bin size constant $\gamma \geq 3c + 9$, this probability is less than $1/N^{c+1}$.

Pulling together the pieces, for $\beta \geq c+3$ and $\gamma \geq 3c+9$, a union bound provides that the probability that we fail to satisfy at least one of the two parts of the definition of *good* is less than $2/N^{c+1} \leq 1/N^c$, satisfying the lemma statement. \square

Now that we have established that good configurations are likely, we establish the below lemma about these configurations that follows directly from the definition of good and the mechanism by which our algorithm updates estimates:

Lemma 6.6. *In an execution with a good configuration with target instance i , no node ever sets its local estimate to a value larger than i . That is, for all u and all rounds, $est_u \leq i$.*

We now continue our analysis by bounding the time required for all nodes to reach the target instance. We do so with two arguments: the first concerning the rounds required for nodes to learn of a larger estimate existing in the system, and the second concerning the rounds required for the largest estimate to increase if it is still less than the target. For the following results, recall that D is the network diameter.

Lemma 6.7. *Fix an execution with a good configuration with target instance i . Assume that at the beginning of round r of this execution the largest estimate in the system is $i_{max} \leq i$. By round $r' = r + O(Dk_{i_{max}} \log^3 N)$ either: the largest estimate in the system is larger than i_{max} , or all nodes have estimate i_{max} .*

Proof. Fix a node u that has $est_u = i_{max}$ at the beginning of round r . If u maintains that estimate at the beginning of its next instance i_{max} phase, then during that phase it will advertise at least one 1-bit (as it has at least its own tag in one of the bins for this instance). It follows that all u 's neighbors in the underlying topology will learn that u has $est_u = i_{max}$ and will upgrade their estimate to i_{max} , if their estimate is currently less than this value. We can then repeat this argument for u 's neighbors, then their neighbors, and so on until either: at least one node adopts a larger estimate than i_{max} (which might impede the application of this logic), or all nodes adopt i_{max} . If the first event occurs, we satisfy the lemma statement. If the first event does not occur, the second event will occur after at most diameter $D + 1$ instance i_{max} phases (the extra phase upper bounds the rounds required between round r and the start of the next instance i_{max} phase). The number of rounds to complete an instance i_{max} phase can be calculated as: $k_{i_{max}}$ bins times $\gamma \log N$ blocks per bin times $\ell + \log N = O(\log N)$ instance i_{max} rounds per block times $\log N$ real rounds for each instance i_{max} rounds. This product evaluates to $O(k_{i_{max}} \log^3 N)$ rounds per instance. Therefore, $O(Dk_{i_{max}} \log^3 N)$ rounds are sufficient to guarantee the lemma statement holds. \square

Lemma 6.8. *Fix an execution with a good configuration with target instance i . Assume that at the beginning of round r of this execution the largest estimate in the system is $i_{max} < i$. By round $r' = r + O(Dk_{i_{max}} \log^3 N)$ the largest estimate in the system is larger than i_{max} .*

Proof. We start by applying Lemma 6.7 to i_{max} and round r . This establishes that by round $r' = r + O(Dk_{i_{max}} \log^3 N)$ rounds either all nodes have estimate i_{max} , or at least one node has an estimate larger than i_{max} . If the latter is true then the lemma is satisfied directly at round r' .

Moving forward, therefore, assume all nodes have the same estimate i_{max} by round r' . By assumption, $i_{max} < i$. It follows that instance i_{max} has at least one crowded bin. Call this bin j . Let T_j be the tags of the $\gamma \log N$ smallest tokens assigned to bin j in instance i_{max} in this configuration. Because nodes spell out tags from order of smallest to largest, we know that any node that knows tags from T_j , will assign each of these tags a block in any execution of instance i_{max} .

It follows, therefore, that in each execution of an i_{max} phase, if all nodes start that phase with an estimate of i_{max} , then *each* of these tags in T_j will spread another hop. Applying the same argument as in the proof of Lemma 6.7, after at most D executions of i_{max} phases, either at least one node has increased its estimate to a value larger than i_{max} , or the tokens in T_j will have spread to all nodes in the network. If the latter event happens, then, by the definition of the algorithm, all nodes will have discovered a crowded bin in instance i_{max} and will increment their estimate. Either way, the lemma is satisfied. Therefore, by round $r' + O(Dk_{i_{max}} \log^3 N) = r + O(Dk_{i_{max}} \log^3 N)$, the conditions of the lemma is satisfied—as required. \square

The following key result leverages Lemmas 6.7 and 6.8 to bound the total rounds required for all nodes to permanently stabilize their estimates to the target instance.

Lemma 6.9. *Fix an execution with a good configuration with target instance i . By round $r = O(Dk_i \log^3 N)$, every node has estimate i . That is, for every node u , $est_u = i$ by round r .*

Proof. By the definition of our algorithm, estimates never decrease. By Lemma 6.6, no node will ever adopt an estimate greater than i . Combined, it follows that we can keep applying Lemma 6.8 to increase the largest estimate until the largest estimate reaches i . We can then apply a single instance of Lemma 6.7 to ensure all nodes have this estimate—at which point the lemma will be permanently satisfied.

To bound the time required for these applications of the above lemmas, we leverage our observation that the largest estimate can only increase. It follows that in the worst case we apply Lemma 6.8 exactly once for each of the estimates leading up to the target i . Because these estimates form a geometric sequence (e.g., 2, 4, 8, ...), the total rounds needed for these applications of Lemma 6.8 is upper bounded by:

$$\begin{aligned} O(Dk_1 \log^3 N) + O(Dk_2 \log^3 N) + \dots + O(Dk_i \log^3 N) &= O((D \log^3 N)(k_1 + k_2 + \dots + k_i)) \\ &= O(Dk_i \log^3 N) \end{aligned}$$

The final application of Lemma 6.7 to spread estimate i to all remaining nodes once it exists in the system adds only a single additional $O(Dk_i \log^3 N)$ rounds. The lemma statement follows. \square

The preceding arguments bound the rounds required for useful information to propagate through the network via the nodes' advertising bits. We now conclude our proof by turning our attention to the rounds required for the actual tokens (which must be passed one at a time through pairwise connections) to spread. We will tackle this problem by picking up where Lemma 6.9 left off: a point at which the system is prepared for the PPUSH instances executing in the second half of blocks to make consistent progress. We will apply our bound on PPUSH from Theorem 6.1 to establish the time required for this final propagation. We will then leverage Theorem 6.2 to replace the network diameter in our complexity with an upper bound expressed with respect to the network size and expansion.

Theorem 6.10. *The CrowdedBin gossip algorithm solves the gossip problem in $O((1/\alpha)k \log^6 N)$ rounds when executed with tag length $b = 1$ in a network with stability $\tau = \infty$.*

Proof. Assume for now that the configuration is good and i its target instance. Let round $r = O(Dk_i \log^3 N)$ be the round specified by Lemma 6.9 for the network to converge its estimate. That is, every node has the same estimate i by round r . By definition, no bin is crowded for instance i in a good configuration. It follows that every tag for every bin in this instance will be spread in every round by the nodes that know that tag in that round. Following the same propagation arguments used in Lemmas 6.7 and 6.8, after at most D more phases of instance i , all nodes will know all tags. This requires at most $O(Dk_i \log^3 N)$ rounds. Therefore by some round $r' = O(Dk_i \log^3 N)$, the system will have reached a *stable* state in which every node has the same estimate i and knows the tag for every token in the system. This information will never again change so we can turn our attention for the rounds required to finish propagating the actual tokens after this point of stabilization.

To bound this token propagation time, fix an arbitrary token t with tag q in instance i . Because we assume the system has stabilized, every node has q assigned to the same block of the same bin in their instance i phase. It follows that if we append together the last $\log N$ rounds from these blocks (i.e., the rounds in which nodes run PPUSH for the tag described in the first ℓ rounds of the block), we obtain a proper execution of PPUSH rumor spreading for token t during these rounds. That is, every time we come to the last $\log N$ rounds of q 's block, all nodes are running PPUSH for rumor t , picking up where they left off in the previous instance.

Applying Theorem 6.1 from above, it follows that with high probability in N , $O(\log^4 N/\alpha)$ rounds are sufficient for t to spread to all nodes after stabilization. Each phase provides $\log N$ rounds of PPUSH, so $O(\log^3 N/\alpha)$ phases are sufficient after stabilization.

The key observation is that each execution of instance i services *all* k rumors after stabilization, as each rumor has its own fixed bin in the instance i phase. Therefore, $O(\log^3 N/\alpha)$ phases are sufficient to spread *all* k rumors in parallel. A union bound establishes that all $k \leq N$ instances succeed with a slightly reduced high probability.

From a probability perspective, we know from Lemma 6.5 that the configuration is good with high probability. We just argued above that if the configuration is good, then with an additional high probability the tokens will all spread in the stated time, once the system stabilizes. We can increase both high probabilities to the desired exponent by increasing the constant β and γ used in the definition of crowded bins, and the constant factor in the time bound for PPUSH. A union bound then shows that both good events occur with high probability.

From round cost perspective, we established that the time to stabilization is at most $O(Dk_i \log^3 N)$ rounds, while the time to complete propagation after stabilization is at most $O(\log^3 N/\alpha)$ instance i phases, which each require $O(k_i \log^3 N)$ rounds. The final time complexity is then in: $O(Dk_i \log^3 N + (k_i \log^6 N)/\alpha)$.

By the definition of a good configuration, we know $k_i \leq 2k$, and by Theorem 6.2, we know $D = O(\log N/\alpha)$. We can therefore simplify this complexity to $O((k \log^6 N)/\alpha)$ rounds, as required. \square

7 ϵ -Gossip with $b = 1$ and $\tau \geq 1$

In this section we consider ϵ -Gossip: a relaxed version of the gossip problem that is parameterized with some ϵ , $0 < \epsilon < 1$ (e.g., as also studied in [7]). In more detail, the problem assumes all n nodes start with a token. To solve ϵ -gossip there must be a subset S of the n nodes in the system, where $|S| \geq \epsilon n$ and for every $u, v \in S$, u knows v 's token and v knows u 's token. Our goal here is to prove that for reasonably well-connected graphs and constant ϵ , *almost* solving gossip can be significantly faster than *fully* solving gossip. In particular, we prove that our SharedBit algorithm from before solves ϵ -gossip in $O\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha}\right)$ rounds. Given that $\Delta \leq n$, this is faster than the $O(n^2)$ required by SharedBit (for $k = n$) when ϵ is a constant fraction and $\alpha = \omega(\log \Delta / (\sqrt{\Delta \log \Delta}))$.

Preliminaries. We restrict our attention in this analysis to the case where $\epsilon \geq 1/2$. We can then handle smaller values for this fraction by applying the below analysis for $\epsilon = 1/2$: a value that (more than) solves the problems for the smaller fraction, and at a cost of at most an extra constant factor in the time complexity (i.e., when we replace $(1 - \epsilon)$ in the denominator with $(1 - 1/2)$, where $\epsilon < 1/2$ is the actual value we are analyzing, the stated bound is less than a factor of two larger than what we would get with the smaller ϵ).

A key tool in our analysis is a set that describes the frequency of different token sets owned by nodes in the network at the beginning of a given round. To do so, let T be the set of tokens in the network. The definition of ϵ -gossip requires that $|T| = n$. For each token subset $S \subseteq T$ and round $r \geq 1$, we define:

$$\text{count}(S, r) = |\{u \in V \mid T_u(r) = S\}|,$$

where $T_u(r)$ is defined the same as in our above SharedBit analysis (i.e., the set of tokens u knows at the beginning of round r). Therefore, $\text{count}(S, r)$ equals the number of nodes with token set S at the beginning of r . We now use the definition of count to define, for each round $r \geq 1$, the following multiset:

$$F(r) = \{(S, q) \mid (S \subseteq T) \wedge (q = \text{count}(S, r)) \wedge (q \geq 1)\}$$

This multiset contains all the token sets that appear at least once in the network at the beginning of round r , along with their frequency of occurrence. Finally, we also make use of the following potential function ϕ , which was first defined in Section 5.1 to analyze SharedBit gossip:

$$\forall r \geq 1 : \phi(r) = \sum_{u \in V} (n - |T_u(r)|).$$

Our analysis will also leverage two useful lemmas from our earlier study of rumor spreading in the mobile telephone model [11]. The first lemma is graph theoretic, and accordingly requires two definitions concerning graph properties. First, for a given graph $G = (V, E)$ and node set $S \subset V$, we define $B_G(S)$ to be the bipartite graph containing all (and only) the edges from E that connect a node in S to a node in $V \setminus S$, with a vertex set consisting of these endpoints. Second, for a given graph H , let $\nu(H)$ the *edge independence number* of H , which describes the size of a maximum matching on H . We now proceed with our lemma:

Lemma 7.1 (Adapted from [11]). *Fix a graph $G = (V, E)$ with $|V| = n$ and vertex expansion α . Fix some $S \subset V$ such that $|S| \leq n/2$. It follows that $\nu(B_G(S)) \geq |S| \cdot (\alpha/4)$.*

The second lemma adapted from [11] is algorithmic in that bounds the performance of a simple randomized strategy for approximating a maximum matching in a bipartite graph:

Lemma 7.2 (Adapted from [11]). *Fix a network topology graph $G = (V, E)$ with maximum degree Δ . Fix some subset $C \subset V$. Assume there is a matching M of size $m \geq 1$ defined over $B_G(C)$. Assume each node in C randomly chooses a neighbor in $B_G(C)$ to send a connection proposal. With constant probability, at least $\Omega(\frac{m}{\sqrt{\Delta \log \Delta}})$ nodes from $V \setminus C$ that are endpoints in M will receive a connection proposal from a node in C .*

Analysis. Our main strategy is to attempt to identify for each round a *coalition* of nodes such that: (1) the size of the coalition is within a target range $(\epsilon/2)n$ to ϵn ; and (2) no node in the coalition has the same token set as a node outside the coalition. If we can find such a coalition, the graph property result captured in Lemma 7.1 tells us that there are many edges between coalition and non-coalition nodes (where the definition of “many” depends on α and ϵ). We can then show that a reasonable fraction of these edges will connect and therefore reduce ϕ . We begin this argument by leveraging the above definitions to prove that either we can find such a coalition or we have already solved the problem.

Lemma 7.3. *Fix a round $r \geq 1$. One of the following must be true about this round: (1) ϵ -gossip is solved by the beginning of round r ; or (2) there exists a $C \subset F(r)$ such that:*

$$(\epsilon/2)n \leq \sum_{(S,q) \in C} q \leq n\epsilon.$$

Proof. Let $q_{max} = \max\{q : (*, q) \in F(r)\}$ (i.e., the number of nodes that own the set owned by the most nodes in r). We consider three cases for q_{max} and show that all three satisfy our lemma.

The first case is that $q_{max} > n\epsilon$. In this case, we have identified a token set S that is owned by more than $n\epsilon$ nodes. Let V_S be the set of nodes that own S at the beginning of r . Because every node starts with its own token in its token set, and no token ever leaves a token set, we know for each $u \in V_S$, u 's token is in S . It follows that every node in V_S knows the token of every other node in this set—meaning we have solved ϵ -gossip and therefore satisfy option (1) from the lemma statement.

The second case is that $(\epsilon/2)n \leq q_{max} \leq n\epsilon$. In this case, we can set $C = \{(S, q_{max})\}$, where S is the set we identified owned by q_{max} nodes (if more than 1, choose one arbitrarily), and directly satisfy option (2) from the lemma statement.

The third and final case is that $q_{max} < (\epsilon/2)n$. In this case, we can apply the following simple greedy strategy for defining C : keep adding pairs from $F(r)$ to C in *decreasing* order of q values until $\sum_{(S,q) \in C} q$ first grows larger than $(\epsilon/2)n$. By our case assumption, every q value in F is less than $(\epsilon/2)n$. Therefore, the

step of the greedy strategy that first pushes us over the $(\epsilon/2)n$ threshold must increase this sum to fall within our target range of $(\epsilon/2)n$ and ϵn . That is, the greedy strategy described above will always terminate having identified a set C that satisfies option (2) from the lemma statement. \square

Repeatedly applying Lemma 7.3 will provide that in each round either we are done with the ϵ -gossip problem or we have a large coalition that is likely to generate lots of progress toward solving the problem. We are now ready to pull together our pieces to prove our main theorem. The main technical contribution of the below proof is arguing that a large coalition likely generates lots of new token transfers. This claim will pull from Lemmas 7.2 and 7.1 from above, as well as Lemma 5.2 from the SharedBit analysis in Section 5.1.

Theorem 7.4. *Fix some ϵ , $0 < \epsilon < 1$. The SharedBit gossip algorithm solves the ϵ -gossip problem in $O\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha}\right)$ rounds when executed with shared randomness with tag length $b = 1$ in a network with stability $\tau \geq 1$.*

Proof. Fix some ϵ that satisfies the theorem statement. Assume w.l.o.g. that $\epsilon \geq 1/2$ (as argued at the beginning of this analysis, if ϵ is smaller, we can apply our analysis for $\epsilon = 1/2$ which more than solves the problem at the cost of only an extra constant factor in the stated time complexity). We begin by focusing on a single round, then extend the argument to the full execution. In particular, fix a round r , $1 \leq r \leq cN^2$ (i.e., a round for which we still have bits in the shared string \hat{r} used by SharedBit). Let $G_r = (V, E)$ be the network topology graph in this round. Assume ϵ -gossip has not finished by the beginning of this round. By Lemma 7.3, there exists a $C \subset F(r)$ such that:

$$(\epsilon/2)n \leq \sum_{(S,q) \in C} q \leq n\epsilon.$$

Let V_C be the set of nodes that start round r with one of the token sets in C . By our above assumption: $(\epsilon/2)n \leq |V_C| \leq n\epsilon$.

Let $q = \min\{|V_C|, |V \setminus V_C|\}$. It follows that $q \leq n/2$. By Lemma 7.1, therefore, there exists a matching M of size $m \geq (\alpha/4)q$ in $B_{G_r}(V_C)$ (the bipartite subgraph of G_r that keeps only edges from E with one endpoint in V_C and one endpoint in $V \setminus V_C$). For each edge $e \in M$, we define $e.c$ to be the endpoint from e in V_C and $e.v$ to be the endpoint from e in $V \setminus V_C$. We say an edge $e \in M$ is *wasted* if both endpoints in e advertise the same bit; i.e., $b_{e.c}(r) = b_{e.v}(r)$. By the definition of the coalition used in Lemma 7.3, it follows for each $e \in M$ it must be the case that $T_{e.c}(r) \neq T_{e.v}(r)$. We can therefore apply Lemma 5.2 which provides that the probability they advertise different bits is $1/2$. The probability that e is wasted is therefore also $1/2$.

To argue more precisely about wasted edges we define some random variables. For each $e \in M$, let X_e be the random indicator variable that evaluates to 1 if e is wasted and otherwise evaluates to 0. Let $Y = \sum_{e \in M} X_e$. By linearity of expectation and our above argument about the probability of wastefulness, it follows: $E(Y) = m/2$.

We now want to bound the probability that the actual number of wasted edges is not too much larger than $E(Y)$. We cannot apply a Chernoff-style bound as there might be dependency between the outcomes of different edges in M (as they may share tokens, and therefore share random bits used to determine their tag). To sidestep these issues, we apply Markov's Inequality (Theorem 2.5 in Section 2) to derive the following:

$$\Pr(Y \geq (3/2) \cdot E(Y)) \leq \frac{E(Y)}{(3/2) \cdot E(Y)} = 2/3.$$

Notice that $(3/2) \cdot E(Y) = (3/4) \cdot m$. We can therefore reword this result to say that with probability at least $1/3$, at least $m/4$ edges in M are not wasted. For clarity, we will subsequently refer to an edge from M that is *not wasted* as an edge that is *primed* (as in the edge is primed for the possibility of its endpoints connecting in a manner that helps spread tokens).

Moving forward in this analysis, assume this event occurs, and therefore at least $m/4$ edges in M are primed. Let $\hat{M} \subseteq M$ be this set of primed edges. (Notice, because $m \geq 1$ and the size of \hat{M} must be a whole number, we know \hat{M} is non-empty under this assumption.)

We want to now apply Lemma 7.2 to the connections described by \hat{M} . To do so, let \hat{C} be the endpoints in \hat{M} that advertise a 1 in this round. Let \hat{G} be the topology graph G_r for this round *modified* such that we remove every node that is not in \hat{C} , but neighbors \hat{C} and also advertises a 1 (along with their incident edges). We emphasize two properties of this modification: (1) by definition, no node in \hat{M} is removed by this step; (2) it is correct to say that nodes in \hat{C} will choose a neighbor from \hat{G} uniformly to send a connection proposal, because the SharedBit algorithm only has nodes that advertise a 1 choose among neighbors that advertise a 0, and we only removed neighbors from \hat{C} nodes that also advertised a 1.

We can therefore apply Lemma 7.2 with $G = \hat{G}$, $C = \hat{C}$, and $M = \hat{M}$. It follows that with constant probability, at least $\Omega(|\hat{M}|/\sqrt{\Delta \log \Delta}) = \Omega(m\sqrt{\Delta \log \Delta})$ nodes in \hat{M} receive a connection proposal from their neighbor in this matching. Each such node u will subsequently connect with *some* node v in this round (though not necessarily its neighbor in \hat{M}). By Lemma 5.2, however, $T_u(r) \neq T_v(r)$ (as each advertised different bits in r), so each of these connections reduces ϕ by at least 1.

Combining our probabilistic events from above, it follows that with constant probability, $\phi(r+1) - \phi(r) \geq \delta \in \Omega(\frac{\alpha q}{\sqrt{\Delta \log \Delta}})$, where, as defined above, $q = \min\{|V_C|, |V \setminus V_C|\}$. Let us call a round in which this event occurs a *good* round. To bound the number of good rounds until ϕ reduces to 0 (and the ϵ -gossip problem is solved, regardless of ϵ), we must first lower bound the size of δ . To do so, we first note that $|V \setminus V_C| \geq (1-\epsilon)n$. It follows that in the case where $q = |V \setminus V_C|$, we know $q \geq (1-\epsilon)n$. On the other hand, if $q = |V_C|$, we can apply our assumption that $\epsilon \geq 1/2$ (see the beginning of this proof) to conclude that $q \geq (1/3)(1-\epsilon)n$. Combined: $(1/3)(1-\epsilon)n$ provides a general lower bound on q for all rounds.

We now know that in a good round r :

$$\phi(r+1) - \phi(r) \geq \delta \in \Omega\left(\frac{\alpha(1-\epsilon)n}{\sqrt{\Delta \log \Delta}}\right).$$

Because $\phi(1) \leq n^2$ and ϕ can only decrease, it follows that

$$n^2/\delta = t_{good} \in O\left(\frac{n\sqrt{\Delta \log \Delta}}{\alpha(1-\epsilon)}\right)$$

good rounds are sufficient to conclude gossip. As established above, the probability of a given round being good is lower bounded by a constant, regardless of the execution history preceding that round. For each round r , let X_r be the random indicator variable that evaluates to 1 if and only if r is good. We know $Pr(X_r = 1) \geq p$, for the constant probability mentioned above. Therefore, in expectation, $t_{good}/p \in \Theta(t_{good})$ rounds are sufficient to achieve t_{good} good rounds. To obtain a high probability result we cannot directly apply a Chernoff bound to these indicator variables as they are not necessarily independent. Each X_r , however, stochastically dominates the trivial random variable \hat{X}_r that evaluates to 1 with probability p . We can then apply a concentration result to the expectation calculated on the \hat{X} variables to determine that $\Theta(t_{good})$ rounds are sufficient, with high probability in n .

Pulling together the pieces, by Lemma 7.3, for each round r , either we have solved ϵ -gossip or we can find a coalition that provides us a constant probability of r being a good round. With high probability, the latter can occur at most $O(t_{good}) = O\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha}\right)$ times before we still solve the problem. \square

The following corollary follows directly from our analysis in Section 5.2 concerning the elimination of the shared randomness assumption when solving gossip with SharedBit.

Corollary 7.5. Fix some ϵ , $0 < \epsilon < 1$. There exists a bit string multiset \mathcal{R}' , such that the *SimSharedBit* gossip algorithm using this \mathcal{R}' solves the ϵ -gossip problem in $O\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha} + (1/\alpha)\Delta^{1/\tau} \log^6 N\right) = \tilde{O}\left(\frac{n\sqrt{\Delta \log \Delta}}{(1-\epsilon)\alpha}\right)$ rounds when executed with tag length $b = 1$ in a network with stability $\tau \geq 1$.

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