

Lecture 14: Algorithms for HMMs

Nathan Schneider

(some slides from Sharon Goldwater;
thanks to Jonathan May for bug fixes)

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Recap: tagging

- POS tagging is a sequence labelling task.
- We can tackle it with a model (HMM) that uses two sources of information:
 - The word itself
 - The tags assigned to surrounding words
- The second source of information means we can't just tag each word independently.

Local Tagging

Words:

Possible tags:
(ordered by
frequency for
each word)

<s>	one	dog	bit	</s>
<s>	CD	NN	NN	</s>
	NN	VB	VBD	
	PRP			

- Choosing the best tag for each word independently, i.e. not considering tag context, gives the wrong answer (<s> CD NN NN </s>).
- Though NN is more frequent for ‘bit’, tagging it as VBD may yield a better *sequence* (<s> CD NN VB </s>)
 - because $P(\text{VBD} | \text{NN})$ and $P(\text{</s>} | \text{VBD})$ are high.

Recap: HMM

- Elements of HMM:
 - Set of states (tags)
 - Output alphabet (word types)
 - Start state (beginning of sentence)
 - State transition probabilities $P(t_i / t_{i-1})$
 - Output probabilities from each state $P(w_i / t_i)$

Recap: HMM

- Given a sentence $\mathbf{W}=w_1\dots w_n$ with tags $\mathbf{T}=t_1\dots t_n$, compute $P(\mathbf{W},\mathbf{T})$ as:

$$P(\mathbf{W}, \mathbf{T}) = \prod_{i=1}^n P(w_i|t_i)P(t_i|t_{i-1})$$

- But we want to find $\operatorname{argmax}_{\mathbf{T}} P(\mathbf{T}|\mathbf{W})$ without enumerating all possible tag sequences \mathbf{T}
 - Use a greedy approximation, or
 - Use Viterbi algorithm to store partial computations.

Greedy Tagging

Words:

Possible tags:
(ordered by
frequency for
each word)

<s>	one	dog	bit	</s>
<s>	CD	NN	NN	</s>
	NN	VB	VBD	
	PRP			

- For $i = 1$ to N : choose the tag that maximizes
 - transition probability $P(t_i|t_{i-1}) \times$
 - emission probability $P(w_i|t_i)$
- This uses tag context but is still suboptimal. Why?
 - It commits to a tag before seeing subsequent tags.
 - It could be the case that ALL possible next tags have low transition probabilities. E.g., if a tag is unlikely to occur at the end of the sentence, that is disregarded when going left to right.

Greedy vs. Dynamic Programming

- The greedy algorithm is **fast**: we just have to make one decision per token, and we're done.
 - Runtime complexity?
 - $O(TN)$ with T tags, length- N sentence
- But subsequent words have no effect on each decision, so the result is likely to be **suboptimal**.
- Dynamic programming search gives an **optimal global** solution, but requires some bookkeeping (= more computation). Postpones decision about any tag until we can be sure it's optimal.

Viterbi Tagging: intuition

Words:

<s>	one	dog	bit	</s>
-----	-----	-----	-----	------

Possible tags:
(ordered by
frequency for
each word)

<s>	CD	NN	NN	</s>
	NN	VB	VBD	
	PRP			

- Suppose we have already computed
 - a) The best tag sequence for <s> ... bit that ends in NN.
 - b) The best tag sequence for <s> ... bit that ends in VBD.
- Then, the best full sequence would be either
 - sequence (a) extended to include </s>, or
 - sequence (b) extended to include </s>.

Viterbi Tagging: intuition

Words:

<s>	one	dog	bit	</s>
-----	-----	-----	-----	------

Possible tags:
(ordered by
frequency for
each word)

<s>	CD	NN	NN	</s>
	NN	VB	VBD	
	PRP			

- But similarly, to get
 - a) The best tag sequence for <s> ... bit that ends in NN.
- We could extend one of:
 - The best tag sequence for <s> ... dog that ends in NN.
 - The best tag sequence for <s> ... dog that ends in VB.
- And so on...

Viterbi: high-level picture

- Want to find $\operatorname{argmax}_{\mathbf{T}} P(\mathbf{T}|\mathbf{W})$
- Intuition: the best path of length i ending in state t must include the best path of length $i-1$ to the previous state. So,
 - Find the best path of length $i-1$ to each state.
 - Consider extending each of those by 1 step, to state t .
 - Take the best of those options as the best path to state t .

Viterbi algorithm

- Use a **chart** to store partial results as we go
 - $T \times N$ table, where $v(t, i)$ is the probability* of the best state sequence for $w_1 \dots w_i$ that ends in state t .

*Specifically, $v(t, i)$ stores the max of the joint probability $P(w_1 \dots w_i, t_1 \dots t_{i-1}, t_i = t | \lambda)$

Viterbi algorithm

- Use a **chart** to store partial results as we go
 - $T \times N$ table, where $v(t, i)$ is the probability* of the best state sequence for $w_1 \dots w_i$ that ends in state t .
- Fill in columns from left to right, with
$$v(t, i) = \max_{t'} v(t', i - 1) \cdot P(t|t') \cdot P(w_i|t_i)$$
 - The max is over each possible previous tag t'
- Store a **backtrace** to show, for each cell, which state at $i - 1$ we came from.

*Specifically, $v(t, i)$ stores the max of the joint probability $P(w_1 \dots w_i, t_1 \dots t_{i-1}, t_i = t | \lambda)$

Transition and Output Probabilities

Transition matrix: $P(t_i | t_{i-1})$:

	Noun	Verb	Det	Prep	Adv	</s>
<s>	.3	.1	.3	.2	.1	0
Noun	.2	.4	.01	.3	.04	.05
Verb	.3	.05	.3	.2	.1	.05
Det	.9	.01	.01	.01	.07	0
Prep	.4	.05	.4	.1	.05	0
Adv	.1	.5	.1	.1	.1	.1

Emission matrix: $P(w_i | t_i)$:

	a	cat	doctor	in	is	the	very
Noun	0	.5	.4	0	.1	0	0
Verb	0	0	.1	0	.9	0	0
Det	.3	0	0	0	0	.7	0
Prep	0	0	0	1.0	0	0	0
Adv	0	0	0	.1	0	0	.9

Example

Suppose W =the doctor is in. Our initially empty table:

v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	$\langle /s \rangle$
Noun					
Verb					
Det					
Prep					
Adv					

Filling in the first column

Suppose W =the doctor is in. Our initially empty table:

v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	$\langle /s \rangle$
Noun	0				
Verb	0				
Det	.21				
Prep	0				
Adv	0				

$$v(\text{Noun, the}) = P(\text{Noun}|\langle s \rangle)P(\text{the}|\text{Noun})=.3(0)$$

$$v(\text{Det, the}) = P(\text{Det}|\langle \ddot{s} \rangle) P(\text{the}|\text{Det})=.3(.7)$$

The second column

$v(\text{Noun, doctor})$

$$= \max_{t'} v(t', \text{the}) \cdot P(\text{Noun}|t') \cdot P(\text{doctor}|\text{Noun})$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	?			
Verb	0				
Det	.21				
Prep	0				
Adv	0				

$$P(\text{Noun}|\text{Det}) P(\text{doctor}|\text{Noun}) = .3(.4)$$


The second column

$v(\text{Noun}, \text{doctor})$

$$= \max_{t'} v(t', \text{the}) \cdot P(\text{Noun}|t') \cdot P(\text{doctor}|\text{Noun})$$

$$= \max \{ 0, 0, .21(.36), 0, 0 \} = .0756$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756			
Verb	0				
Det	.21				
Prep	0				
Adv	0				



$$P(\text{Noun}|\text{Det}) P(\text{doctor}|\text{Noun}) = .9(.4)$$


The second column

$v(\text{Verb}, \text{doctor})$

$$= \max_{t'} v(t', \text{the}) \cdot P(\text{Verb}|t') \cdot P(\text{doctor}|\text{Verb})$$

$$= \max \{ 0, 0, .21(.001), 0, 0 \} = .00021$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756			
Verb	0	.00021			
Det	.21				
Prep	0				
Adv	0				



$$P(\text{Verb}|\text{Det}) P(\text{doctor}|\text{Verb}) = .01(.1)$$


The second column

$v(\text{Verb}, \text{doctor})$

$$= \max_{t'} v(t', \text{the}) \cdot P(\text{Verb}|t') \cdot P(\text{doctor}|\text{Verb})$$

$$= \max \{ 0, 0, .21(.001), 0, 0 \} = .00021$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756			
Verb	0	.00021			
Det	.21	0			
Prep	0	0			
Adv	0	0			



$$P(\text{Verb}|\text{Det}) P(\text{doctor}|\text{Verb}) = .01(.1)$$

The third column

$v(\text{Noun}, \text{is})$

$$= \max_{t'} v(t', \text{doctor}) \cdot P(\text{Noun}|t') \cdot P(\text{is}|\text{Noun})$$

$$= \max \{ .0756(.02), .00021(.03), 0, 0, 0 \} = .001512$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756	.001512		
Verb	0	.00021			
Det	.21	0			
Prep	0	0			
Adv	0	0			

$$P(\text{Noun}|\text{Noun}) P(\text{is}|\text{Noun}) = .2(.1) = .02$$

$$P(\text{Noun}|\text{Verb}) P(\text{is}|\text{Noun}) = .3(.1) = .03$$

The third column

$v(\text{Verb}, \text{is})$

$$= \max_{t'} v(t', \text{doctor}) \cdot P(\text{Verb}|t') \cdot P(\text{is}|\text{Verb})$$
$$= \max \{ .0756(.36), .00021(.045), 0, 0, 0 \} = .027216$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756	.001512		
Verb	0	.00021	.027216		
Det	.21	0	0		
Prep	0	0	0		
Adv	0	0	0		

$$P(\text{Verb}|\text{Noun}) P(\text{is}|\text{Verb}) = .4(.9) = .36$$

$$P(\text{Verb}|\text{Verb}) P(\text{is}|\text{Verb}) = .05(.9) = .045$$

The fourth column

$v(\text{Prep}, \text{in})$

$$= \max_{t'} v(t', \text{is}) \cdot P(\text{Prep}|t') \cdot P(\text{in}|\text{Prep})$$

$$= \max \{ .001512(.3), .027216(.2), 0, 0, 0 \} = .005443$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756	.001512	0	
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0		

$$P(\text{Prep}|\text{Noun}) P(\text{in}|\text{Prep}) = .3(1.0)$$

$$P(\text{Prep}|\text{Verb}) P(\text{in}|\text{Prep}) = .2(1.0)$$

The fourth column

$v(\text{Prep}, \text{in})$

$$= \max_{t'} v(t', \text{is}) \cdot P(\text{Prep}|t') \cdot P(\text{in}|\text{Prep})$$

$$= \max \{ .000504(.004), .027216(.01), 0, 0, 0 \} = .000272$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$\langle /s \rangle$
Noun	0	.0756	.001512	0	
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	

$$P(\text{Adv}|\text{Noun}) P(\text{in}|\text{Adv}) = .04(.1)$$

$$P(\text{Adv}|\text{Verb}) P(\text{in}|\text{Adv}) = .1(.1)$$

End of sentence

$v(</s>)$

$$= \max_{t'} v(t', \text{in}) \cdot P(</s>|t')$$

$$= \max \{ 0, 0, 0, .005443(0), .000272(.1) \} = .0000272$$

v	$w_1=\text{the}$	$w_2=\text{doctor}$	$w_3=\text{is}$	$w_4=\text{in}$	$</s>$
Noun	0	.0756	.001512	0	$.0000272$ 2
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	

$$P(</s>|\text{Prep})=0$$

$$P(</s>|\text{Adv})=.1$$

Completed Viterbi Chart

v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	$\langle /s \rangle$
Noun	0	.0756	.001512	0	.000027 2
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	

Following the Backtraces

v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	$\langle /s \rangle$
Noun	0	.0756	.001512	0	.000027 2
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	

The diagram illustrates backtraces from the final state to the initial state. Red arrows point from the final state to the initial state for the following transitions: Noun to Verb, Verb to Det, Det to Noun, and Verb to Adv. A blue arrow points from the final state to the Adv state.

Following the Backtraces

v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	$\langle /s \rangle$
Noun	0	.0756	.001512	0	.000027 2
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	

The diagram illustrates backtraces from the end token $\langle /s \rangle$ to the word 'the'. Red arrows show the path from $\langle /s \rangle$ to the 'the' cell in the Verb row, then to the 'the' cell in the Noun row, and finally to the 'the' cell in the Det row. Blue arrows show the path from $\langle /s \rangle$ to the 'is' cell in the Verb row, then to the 'is' cell in the Adv row, and finally to the 'is' cell in the Prep row.

Following the Backtraces

v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	$\langle /s \rangle$
Noun	0	.0756	.001512	0	.000027 2
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	

The diagram illustrates backtraces from the end token $\langle /s \rangle$ to the word 'the'. Red arrows show a path from $\langle /s \rangle$ to the 'Det' row (value .21), then to the 'Noun' row (value .0756), and finally to the w_1 column (value 0). Blue arrows show a path from $\langle /s \rangle$ to the 'Verb' row (value .027216), then to the 'Noun' row (value .001512), and finally to the w_1 column (value 0).

Following the Backtraces

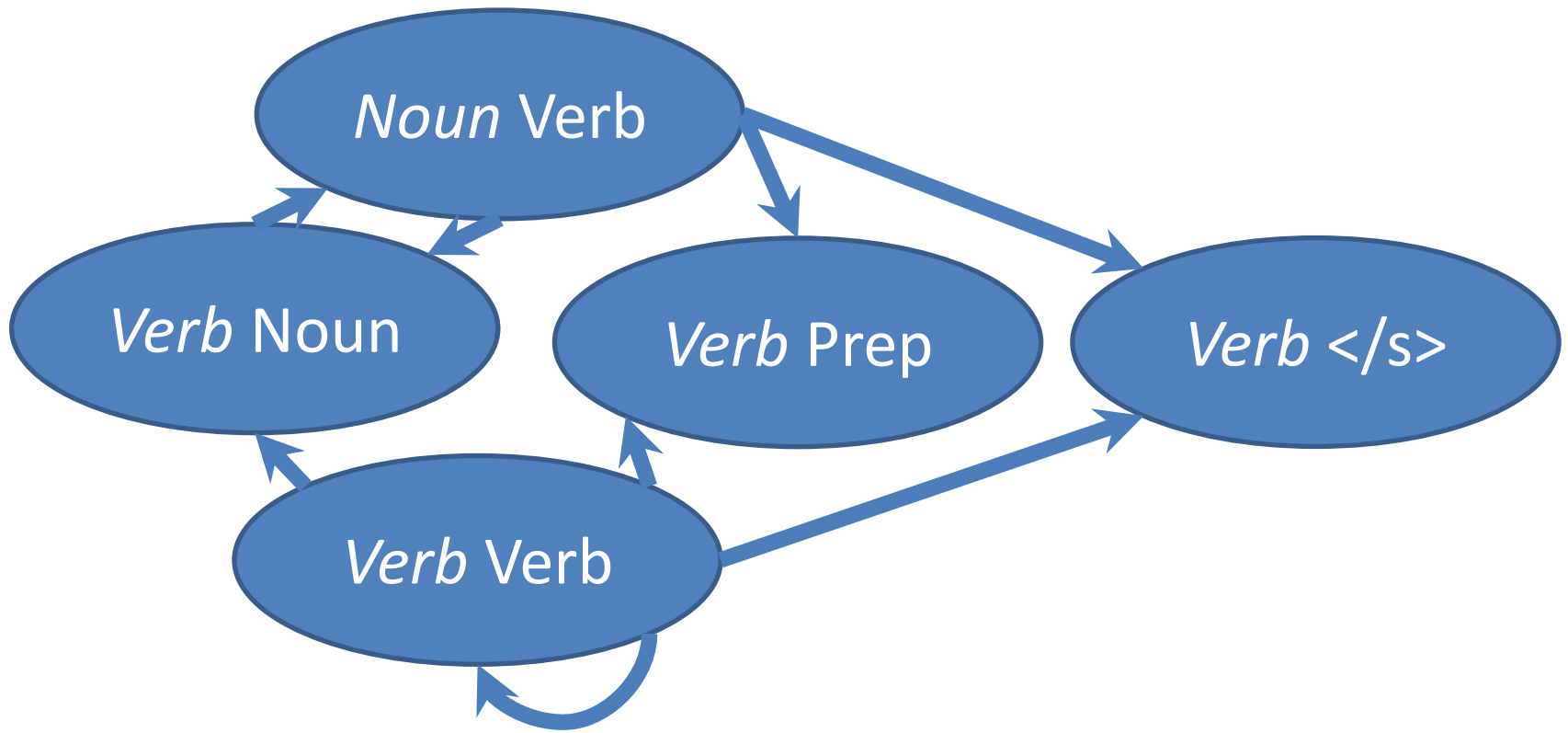
v	w_1 =the	w_2 =doctor	w_3 =is	w_4 =in	</s>
Noun	0	.0756	.001512	0	.000027 2
Verb	0	.00021	.027216	0	
Det	.21	0	0	0	
Prep	0	0	0	.005443	
Adv	0	0	0	.000272	
	Det	Noun	Verb	Prep	

Implementation and efficiency

- For sequence length N with T possible tags,
 - Enumeration takes $O(T^N)$ time and $O(N)$ space.
 - Bigram Viterbi takes $O(T^2N)$ time and $O(TN)$ space.
 - Viterbi is exhaustive: further speedups might be had using methods that prune the search space.
- As with N-gram models, chart probs get really tiny really fast, causing underflow.
 - So, we use **costs** (neg log probs) instead.
 - Take minimum over sum of costs, instead of maximum over product of probs.

Higher-order Viterbi

- For a tag **trigram** model with **T** possible tags, we effectively need **T^2** states
 - **n**-gram Viterbi requires **T^{n-1}** states, takes **$O(T^n N)$** time and **$O(T^{n-1} N)$** space.



HMMs: what else?

- Using Viterbi, we can find the best tags for a sentence (**decoding**), and get $P(\mathbf{W}, \mathbf{T})$.
- We might also want to
 - Compute the **likelihood** $P(\mathbf{W})$, i.e., the probability of a sentence regardless of its tags (a language model!)
 - **learn** the best set of parameters (transition & emission probs.) given only an *unannotated* corpus of sentences.

Computing the likelihood

- From probability theory, we know that

$$P(\mathbf{W}) = \sum_{\mathbf{T}} P(\mathbf{W}, \mathbf{T})$$

- There are an exponential number of \mathbf{T} s.
- Again, by computing and storing partial results, we can solve efficiently.
- *(Advanced slides show the algorithm for those who are interested!)*

Summary

- HMM: a generative model of sentences using hidden state sequence
- Greedy tagging: fast but suboptimal
- Dynamic programming algorithms to compute
 - Best tag sequence given words (**Viterbi algorithm**)
 - Likelihood (forward algorithm—*see advanced slides*)
 - Best parameters from unannotated corpus (forward-backward algorithm, an instance of EM—*see advanced slides*)

Advanced Topics

(the following slides are just for people who are interested)

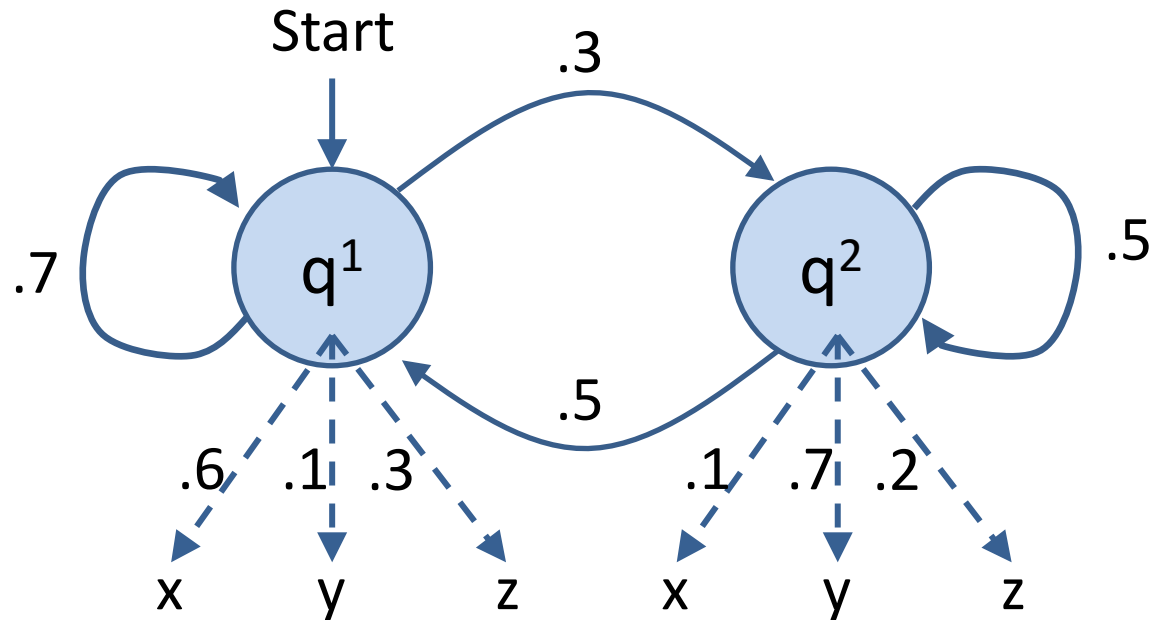
Notation

- Sequence of observations over time o_1, o_2, \dots, o_N
 - here, words in sentence
- Vocabulary size V of possible observations
- Set of possible states q^1, q^2, \dots, q^T (see note next slide)
 - here, tags
- A , an $T \times T$ matrix of transition probabilities
 - a_{ij} : the prob of transitioning from state i to j .
- B , an $T \times V$ matrix of output probabilities
 - $b_i(o_t)$: the prob of emitting o_t from state i .

Note on notation

- J&M use q_1, q_2, \dots, q_N for set of states, but *also* use q_1, q_2, \dots, q_N for state sequence over time.
 - So, just seeing q_1 is ambiguous (though usually disambiguated from context).
 - I'll instead use q^i for state names, and q_n for state at time n .
 - So we could have $q_n = q^i$, meaning: the state we're in at time n is q^i .

HMM example w/ new notation



- States $\{q^1, q^2\}$ (or $\{\langle s \rangle, q^1, q^2\}$): think *NN*, *VB*
- Output symbols $\{x, y, z\}$: think *chair*, *dog*, *help*

HMM example w/ new notation

- A possible sequence of outputs for this HMM:

z y y x y z x z z

- A possible sequence of states for this HMM:

$q^1 q^2 q^2 q^1 q^1 q^2 q^1 q^1 q^1$

- For these examples, $N = 9$, $q_3 = q^2$ and $o_3 = y$

Transition and Output Probabilities

- Transition matrix **A**:

$$a_{ij} = P(q^j | q^i)$$

$$\text{Ex: } P(q_n = q^2 | q_{n-1} = q^1) = .3$$

	q^1	q^2
$\langle s \rangle$	1	0
q^1	.7	.3
q^2	.5	.5

- Output matrix **B**:

$$b_i(o) = P(o | q^i)$$

$$\text{Ex: } P(o_n = y | q_n = q^1) = .1$$

	x	y	z
q^1	.6	.1	.3
q^2	.1	.7	.2

Forward algorithm

- Use a table with cells $\alpha(j,t)$: the probability of being in state j after seeing $o_1 \dots o_t$ (**forward probability**).

$$\alpha(j, t) = P(o_1, o_2, \dots, o_t, q_t = j | \lambda)$$

- Fill in columns from left to right, with

$$\alpha(j, t) = \sum_{i=1}^N \alpha(i, t-1) \cdot a_{ij} \cdot b_j(o_t)$$

- Same as Viterbi, but sum instead of max (and no backtrace).

Note: because there's a sum, we can't use the trick that replaces probs with costs. For implementation info, see <http://digital.cs.usu.edu/~cyan/CS7960/hmm-tutorial.pdf> and <http://stackoverflow.com/questions/13391625/underflow-in-forward-algorithm-for-hmms>.

Example

- Suppose $0=xzy$. Our initially empty table:

	$o_1=x$	$o_2=z$	$o_3=y$
q^1			
q^2			

Filling the first column

	$o_1=x$	$o_2=z$	$o_3=y$
q^1	.6		
q^2	0		

$$\alpha(1,1) = a_{\langle s \rangle_1} \cdot b_1(x) = (1)(.6)$$

$$\alpha(2,1) = a_{\langle s \rangle_2} \cdot b_2(x) = (0)(.1)$$

Starting the second column

	$o_1=x$	$o_2=z$	$o_3=y$
q^1	.6	.126	
q^2	0		

$$\begin{aligned}\alpha(1,2) &= \sum_{i=1}^N \alpha(i,1) \cdot a_{i1} \cdot b_1(z) \\ &= \alpha(1,1) \cdot a_{11} \cdot b_1(z) + \alpha(2,1) \cdot a_{21} \cdot b_1(z) \\ &= (.6)(.7)(.3) + (0)(.5)(.3) \\ &= .126\end{aligned}$$

Finishing the second column

	$o_1=x$	$o_2=z$	$o_3=y$
q^1	.6	.126	
q^2	0	.036	

$$\begin{aligned}\alpha(2,2) &= \sum_{i=1}^N \alpha(i,1) \cdot a_{i2} \cdot b_2(z) \\ &= \alpha(1,1) \cdot a_{12} \cdot b_2(z) + \alpha(2,1) \cdot a_{22} \cdot b_2(z) \\ &= (.6)(.3)(.2) + (0)(.5)(.2) \\ &= .036\end{aligned}$$

Third column and finish

	$o_1=x$	$o_2=z$	$o_3=y$
q^1	.6	.126	.01062
q^2	0	.036	.03906

- Add up all probabilities in last column to get the probability of the entire sequence:

$$P(O|\lambda) = \sum_{i=1}^N \alpha(i, T)$$

Learning

- Given *only* the output sequence, learn the best set of parameters $\lambda = (A, B)$.
- Assume 'best' = maximum-likelihood.
- Other definitions are possible, won't discuss here.

Unsupervised learning

- Training an HMM from an annotated corpus is simple.
 - **Supervised** learning: we have examples labelled with the right 'answers' (here, tags): no hidden variables in training.
- Training from unannotated corpus is trickier.
 - **Unsupervised** learning: we have no examples labelled with the right 'answers': all we see are outputs, state sequence is hidden.

Circularity

- If we know the state sequence, we can find the best λ .
 - E.g., use MLE: $P(q^j|q^i) = \frac{C(q^i \rightarrow q^j)}{C(q^i)}$
- If we know λ , we can find the best state sequence.
 - use Viterbi
- But we don't know either!

Expectation-maximization (EM)

As in spelling correction, we can use EM to bootstrap, iteratively updating the parameters and hidden variables.

- Initialize parameters $\lambda^{(0)}$
- At each iteration k ,
 - E-step: Compute **expected counts** using $\lambda^{(k-1)}$
 - M-step: Set $\lambda^{(k)}$ using MLE on the expected counts
- Repeat until λ doesn't change (or other stopping criterion).

Expected counts??

Counting transitions from $q^i \rightarrow q^j$:

- Real counts:
 - count 1 each time we see $q^i \rightarrow q^j$ in true tag sequence.
- Expected counts:
 - With current λ , compute probs of all possible tag sequences.
 - If sequence Q has probability p , count p for each $q^i \rightarrow q^j$ in Q .
 - Add up these fractional counts across all possible sequences.

Example

- Notionally, we compute expected counts as follows:

Possible sequence				Probability of sequence
$Q_1 =$	q^1	q^1	q^1	p_1
$Q_2 =$	q^1	q^2	q^1	p_2
$Q_3 =$	q^1	q^1	q^2	p_3
$Q_4 =$	q^1	q^2	q^2	p_4
Observs:	x	z	y	

Example

- Notionally, we compute expected counts as follows:

Possible sequence				Probability of sequence
$Q_1 =$	q^1	q^1	q^1	p_1
$Q_2 =$	q^1	q^2	q^1	p_2
$Q_3 =$	q^1	q^1	q^2	p_3
$Q_4 =$	q^1	q^2	q^2	p_4
Observs:	x	z	y	

$$\hat{C}(q^1 \rightarrow q^1) = 2p_1 + p_3$$

Forward-Backward algorithm

- As usual, avoid enumerating all possible sequences.
- **Forward-Backward** (Baum-Welch) algorithm computes expected counts using forward probabilities and **backward probabilities**:

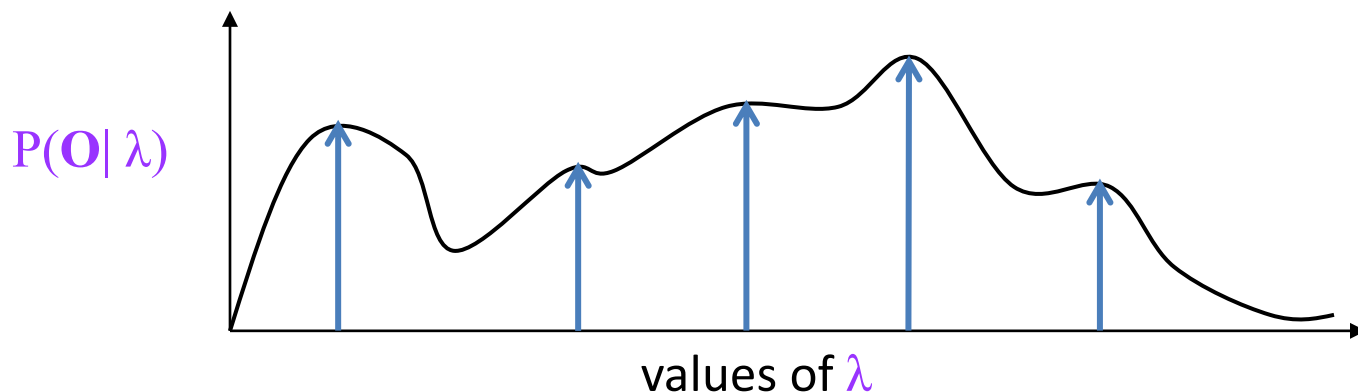
$$\beta(j, t) = P(q_t = j, o_{t+1}, o_{t+2}, \dots, o_T | \lambda)$$

– Details, see J&M 6.5

- EM idea is much more general: can use for many latent variable models.

Guarantees

- EM is guaranteed to find a **local** maximum of the likelihood.



- Not guaranteed to find **global** maximum.
- Practical issues: initialization, random restarts, early stopping. Fact is, it doesn't work well for learning POS taggers!