Lecture 5

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- Answer: Arithmetize $oldsymbol{arphi}$
 - i.e., replace arphi with an **arithmetic** circuit computing extension g
 - Go gate-by-gate through φ , replacing each gate with the gate's multilinear extension.
 - $NOT(x) \rightarrow 1 x$
 - $AND(x, y) \rightarrow x \cdot y$
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Transforming a Boolean formula φ of size S into an arithmetic circuit computing an extension g of φ .

Note: $deg(g) \leq S$, and g can be evaluated at any input, gate by gate, in time O(S).

Costs of #SAT Protocol Applied to g

• Let φ be a Boolean formula of size S over n variables, g the extension obtained by arithmetizing φ .

Rounds	Communication	V Time	P Time	
n	P sends a degree S	• $O(S)$ time to process each	P evaluates g at	
	polynomial in reach round,	of the n messages of P	$O(S \cdot 2^n)$ points	
	V sends one field element	• $O(S)$ time to evaluate	to determine each	
	in each round	g(r)	message	
	\Rightarrow	\Rightarrow	\Rightarrow	
	$O(S \cdot n)$	$O(S \cdot n)$ time total	$O(S^2 \cdot n \cdot 2^n)$	
	field elements sent in		time in total.	
	total.			

Details of Prover's Computation

$$H_i(X_i) := \sum_{b_i \in \{0,1\}} \dots \sum_{b_n \in \{0,1\}} g(r_1, r_2, \dots, r_{i-1}, X_i, b_{i+1}, b_{i+2}, \dots, b_n)$$

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- H_i has degree d = O(S) because g has degree O(S) in each of its n variables.
- To specify any degree d polynomial it suffices to specify the polynomial's evaluations at inputs in [d]: = {0, 1, 2, ..., d}.

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- Recalling that g can be evaluated at any input in O(S) time, this means H_i can be evaluated at all inputs in [d] in time $O(S^2 2^{n-i})$ time.
- Across all *n* rounds, this is $O(\sum_{i=1}^n S^2 2^{n-i}) = O(S^2 2^n)$ time.

- #SAT is a **#P**-complete problem.
 - Hence, the protocol we just saw implies that **every** problem in **#P** has an interactive proof with a polynomial time verifier.
- It is not much harder to show that this in fact holds for every problem in **PSPACE** [LFKN, Shamir].

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 - No. The main reason: P's runtime.
 - When applying the protocols of [LFKN, Shamir] even to very simple problems, the honest prover would require **superpolynomial** time.
 - The #SAT prover took time at least 2^n .
 - This seems unavoidable for #SAT, since we don't know how to even solve the problem in less than 2^n time.
 - But we can hope to solve "easier" problems without turning those problems into #SAT instances.

Doubly-Efficient Interactive Proofs

Doubly-Efficient Interactive Proof

- A doubly-efficient interactive proof for a problem is one where:
 - V runs in time linear in the input size.
 - Pruns in polynomial time.



A Second Application of the Sum-Check Protocol

A Doubly-Efficient Interactive Proof for Counting Triangles

- Input: $A \in \{0,1\}^{n \times n}$, representing the adjacency matrix of a graph.
- Desired Output: $\frac{1}{6} \cdot \sum_{(i,j,k) \in [n]^3} A_{ij} A_{jk} A_{ik}$.
- Fastest known algorithm runs in matrix-multiplication time, currently about $n^{2.37}$.

- Input: $A \in \{0,1\}^{n \times n}$, representing the adjacency matrix of a graph.
- Desired Output: $\frac{1}{6} \cdot \sum_{(i,j,k) \in [n]^3} A_{ij} A_{jk} A_{ik}$.
- The Protocol:
 - View *A* as a function mapping $\{0,1\}^{\log n} \times \{0,1\}^{\log n}$ to *F*.
 - Recall that \tilde{A} denotes the multilinear extension of A.
 - Define the polynomial $g(X, Y, Z) = \tilde{A}(X, Y) \tilde{A}(Y, Z) \tilde{A}(X, Z)$
 - Apply the sum-check protocol to *g* to compute:

$$\sum_{(a,b,c) \in \{0,1\}^{3\log n}} g(a,b,c)$$

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 - Define the polynomial $g(X, Y, Z) = \tilde{A}(X, Y) \tilde{A}(Y, Z) \tilde{A}(X, Z)$
 - Apply the sum-check protocol to g to compute:

$$\sum_{(a,b,c)\in\{0,1\}^{3\log n}}g(a,b,c$$

- Costs:
 - Total communication is $O(\log n)$, V runtime is $O(n^2)$, P runtime is $O(n^3)$.
 - V's runtime dominated by evaluating: $g(r_1, r_2, r_3) = \tilde{A}(r_1, r_2) \tilde{A}(r_2, r_3) \tilde{A}(r_1, r_3).$

Third Application of the Sum-Check Protocol

A Doubly-Efficient Interactive Proof for Matrix Multiplication

[Thaler13]: Optimal IP For n x n MatMult

• Goal: Given $n \times n$ input matrices A, B over field F, compute $C = A \cdot B$.

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- Goal: Given $n \times n$ input matrices A, B over field F, compute $C = A \cdot B$.
- P simply determines the "right answer", and then P does $O(n^2)$ extra work to prove its correctness.
- Optimal runtime up to leading constant assuming no $O(n^2)$ time algorithm for MatMult.
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- V runs in linear time (which is also optimal).

Problem Size	Naïve MatMult Time	Additional P time	V Time	Rounds	Protocol Comm
1024 x 1024	2.17 s	0.03 s	0.09 s	11	264 bytes
2048 x 2048	18.23 s	0.13 s	0.30 s	12	288 bytes

Comparison to Freivalds' Algorithm

- Recall that Freivalds in 1979 gave the following protocol for MatMult. To check $A \cdot B = D$:
 - V picks random vector *x*.
 - Accepts if $A \cdot (Bx) = Dx$.
 - No extra work for P, $O(n^2)$ time for V.

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 - Accepts if $A \cdot (Bx) = Dx$.
 - No extra work for P, $O(n^2)$ time for V.
- Our big win: verifying algorithms that invoke MatMult, but aren't really interested in matrices.
 - E.g., Best-known subgraph-counting algorithms square the adjacency matrix, but are only interested in a single number.
 - Total communication for us is $O(\log n)$, Freivalds' is $\Omega(n^2)$.

MatMult Protocol: Technical Details

Notation

- Given $n \times n$ input matrices A, B over field F, interpret Aand B as functions mapping $\{0,1\}^{\log n} \times \{0,1\}^{\log n}$ to Fvia $A(i_1, \dots, i_{\log n}, j_1, \dots, j_{\log n}) = A_{ij}$.
- Let $C = A \cdot B$ denote the true answer.
- Let \tilde{A} , \tilde{B} denote the multilinear extensions of the functions A and B.

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- By Schwartz-Zippel: it is safe for V to believe that D equals the correct answer C as long as $\tilde{D}(r_1, r_2) = \tilde{C}(r_1, r_2)$.

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- This implies the following **polynomial** identity: $\tilde{a}(t, t) = \tilde{b}(t, t)$

$$\tilde{C}(\boldsymbol{i},\boldsymbol{j}) = \sum_{\boldsymbol{k}\in\{0,1\}}\log n \ \tilde{A}(\boldsymbol{i},\boldsymbol{k})\tilde{B}(\boldsymbol{k},\boldsymbol{j}).$$

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- This implies the following **polynomial** identity:

$$\tilde{C}(\boldsymbol{i},\boldsymbol{j}) = \sum_{\boldsymbol{k}\in\{0,1\}^{\log n}} \tilde{A}(\boldsymbol{i},\boldsymbol{k})\tilde{B}(\boldsymbol{k},\boldsymbol{j}).$$

• So V applies sum-check protocol to compute

$$\tilde{C}(\boldsymbol{r_1}, \boldsymbol{r_2}) = \sum_{b_1 \in \{0,1\}} \dots \sum_{b_{\log n} \in \{0,1\}} g(b_1, \dots, b_{\log n}),$$

where:
$$g(\boldsymbol{z}) := \tilde{A}(\boldsymbol{r_1}, \boldsymbol{z}) \ \tilde{B}(\boldsymbol{z}, \boldsymbol{r_2}).$$

Making V Fast

• At end of sum-check, V must evaluate

$$g(\boldsymbol{r_3}) = \tilde{A}(\boldsymbol{r_1}, \boldsymbol{r_3}) \ \tilde{B}(\boldsymbol{r_3}, \boldsymbol{r_2}).$$

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- Recall that each evaluation can be computed in $O(n^2)$ time.

- Recall: we're using sum-check to compute $\sum_{b_1 \in \{0,1\}} \dots \sum_{b_{\log n} \in \{0,1\}} g(b_1, \dots, b_{\log n}).$
- Round *i*: P sends quadratic polynomial S_i(X_i) claimed to equal: ∑_{bi+1∈{0,1}} ... ∑_{blog n∈{0,1}} g(r_{3,1}, ..., r_{3,i-1}, X_i, b_{i+1}, ..., b_{log n})
 Suffices for P to specify s_i(0), s_i(1), s_i(2)

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 Suffices for P to specify s_i(0), s_i(1), s_i(2)
 - Thus: Enough for P to evaluate g at all points of the form $(r_{3,1}, ..., r_{3,i-1}, \{0,1,2\}, b_{i+1}, ..., b_{\log n})$: $b_{i+1}, ..., b_{\log n} \in \{0,1\}^{\log n - i}$

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 This is O(ⁿ/_{2i}) points.
 - Recall \tilde{A} and \tilde{B} can each be evaluated at any input in $O(n^2)$ time, and hence so can g.

• So P can compute
$$S_i$$
 in $O\left(\frac{n}{2^i} \cdot n^2\right) = O\left(n^3/2^i\right)$ time.

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 - This is $O(\frac{n}{2^i})$ points.
 - Recall \tilde{A} and \tilde{B} can each be evaluated at any input in $O(n^2)$ time, and hence so can g.
- Over all rounds, this is $O(\sum_i n^3/2^i) = O(n^3)$ total time.

Making P Fast: Second Attempt

- Recall: Enough to evaluate *g* at all points of the form: $z = (r_{3,1}, ..., r_{3,i-1}, \{0,1,2\}, b_{i+1}, ..., b_{\log n}): b_{i+1}, ..., b_{\log n} \in \{0,1\}^{\log n-i}$
- Already showed: how to do this in $O(n^3/2^i)$ time.
- Can we improve this to $O(n^2)$ time?

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- Already showed: how to do this in $O(n^3/2^i)$ time.
- Can we improve this to $O(n^2)$ time?
- Key observation each entry A_{ij} contributes to $\tilde{A}(r_1, z)$ for less than 3 tuples z of the above form.
 - Similarly entry B_{ij} contributes to $\tilde{B}(\boldsymbol{z}, \boldsymbol{r_2})$ for less than 3 tuples \boldsymbol{z} of the above form.

A Fourth Application of the Sum-Check Protocol

A **Better** Doubly-Efficient Interactive Proof for Counting Triangles

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A **Better** Doubly-Efficient Interactive Proof for Counting Triangles

- In our first IP for counting triangles, V's runtime is $O(n^2)$, P's runtime was $O(n^3)$.
- We now give an IP for the same problem where P runs the fastest known algorithm for counting triangles, and then does $O(n^2)$ extra work to prove the answer is correct.

- Input: $A \in \{0,1\}^{n \times n}$, representing the adjacency matrix of a graph.
- Desired Output: $\frac{1}{6} \cdot \sum_{(i,j,k) \in [n]^3} A_{ij} A_{jk} A_{ki}$
 - $= \frac{1}{6} \cdot \sum_{(i,j) \in [n]^2} (A^2)_{ij} \cdot A_{ij}.$

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- Define the polynomial $h(X, Y) = (\widetilde{A^2})(X, Y) \tilde{A}(X, Y)$.

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 - Apply the sum-check protocol to *h*.
 - At the end of the protocol, V needs to evaluate: $h(r_1, r_2) = \widetilde{(A^2)}(r_1, r_2) \widetilde{A}(r_1, r_2).$
 - V can evaluate $\tilde{A}(r_1, r_2)$ on its own in $O(n^2)$ time. V uses the MatMult protocol to force P to compute $\widetilde{(A^2)}(r_1, r_2)$ for her.